

# Orthogonal Basis

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# Announcement

- 本週四 (5/19) 公告第三次作業
- 下週四 (5/26) 第二次小考
  - 範圍：第五章
- 已勾第五章習題
  - [http://speech.ee.ntu.edu.tw/~tlkagk/courses/LA\\_2016/Lecture/problem.pdf](http://speech.ee.ntu.edu.tw/~tlkagk/courses/LA_2016/Lecture/problem.pdf)

# Outline

Orthogonal/Orthonormal Basis

Orthogonal Decomposition Theory

How to find Orthonormal Basis

Reference: Textbook Chapter 7.2, 7.3

# Orthogonal Basis

- A set of vectors is called an orthogonal set if every pair of distinct vectors in the set is orthogonal.
- A set of vectors is called an orthonormal set if it is an orthogonal set, and the norm of all the vectors is 1
- A basis that is an orthogonal (orthonormal) set is called an orthogonal (orthonormal) basis

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Orthogonal basis of  $\mathbb{R}^3$

Orthonormal basis of  $\mathbb{R}^3$

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# Orthogonal Basis

- Let  $S = \{v_1, v_2, \dots, v_k\}$  be an orthogonal basis for a subspace  $W$ , and let  $u$  be a vector in  $W$ .

$$u = c_1 v_1 + c_2 v_2 + \dots + c_k v_k$$
$$\frac{u \cdot v_1}{\|v_1\|^2} \quad \frac{u \cdot v_2}{\|v_2\|^2} \quad \frac{u \cdot v_k}{\|v_k\|^2}$$

**Proof**

To find  $c_i$

How about orthonormal basis?

$$\begin{aligned} u \cdot v_i &= (c_1 v_1 + c_2 v_2 + \dots + c_i v_i + \dots + c_k v_k) \cdot v_i \\ &= c_1 v_1 \cdot v_i + c_2 v_2 \cdot v_i + \dots + c_i v_i \cdot v_i + \dots + c_k v_k \cdot v_i \\ &= c_i (v_i \cdot v_i) = c_i \|v_i\|^2 \quad \longrightarrow \quad c_i = \frac{u \cdot v_i}{\|v_i\|^2} \end{aligned}$$

# Example

- Example:  $\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is an orthogonal basis for  $\mathcal{R}^3$

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 5 \\ -4 \\ 1 \end{bmatrix}$$

$$\text{Let } \mathbf{u} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \text{ and } \mathbf{u} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3.$$

$c_1$

$c_2$

$c_3$

.. ..

# Orthogonal Projection

- Let  $S = \{v_1, v_2, \dots, v_k\}$  be an orthogonal basis for a subspace  $W$ , and let  $u$  be a vector in  $W$ .

$$u = c_1 v_1 + c_2 v_2 + \dots + c_k v_k$$
$$\frac{u \cdot v_1}{\|v_1\|^2} \quad \frac{u \cdot v_2}{\|v_2\|^2} \quad \frac{u \cdot v_k}{\|v_k\|^2}$$

- Let  $u$  be any vector, and  $w$  is the orthogonal projection of  $u$  on  $W$ .

$$w = c_1 v_1 + c_2 v_2 + \dots + c_k v_k$$
$$\frac{u \cdot v_1}{\|v_1\|^2} \quad \frac{u \cdot v_2}{\|v_2\|^2} \quad \frac{u \cdot v_k}{\|v_k\|^2}$$



# Orthogonal Projection

- Let  $S = \{v_1, v_2, \dots, v_k\}$  be an orthogonal basis for a subspace  $W$ . Let  $u$  be any vector, and  $w$  is the orthogonal projection of  $u$  on  $W$ .

$$P_W = C(C^T C)^{-1} C^T$$

$$C^T = \begin{bmatrix} v_1^T \\ v_2^T \\ \vdots \\ v_n^T \end{bmatrix}$$

$$C = [v_1 \quad \dots \quad v_n]$$

$$w = \underbrace{c_1}_{\frac{u \cdot v_1}{\|v_1\|^2}} v_1 + \underbrace{c_2}_{\frac{u \cdot v_2}{\|v_2\|^2}} v_2 + \dots + \underbrace{c_k}_{\frac{u \cdot v_k}{\|v_k\|^2}} v_k$$

$$P_W = CDC^T$$

Projected:

$$w = CDC^T u$$

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# Orthogonal Basis

Let  $\{u_1, u_2, \dots, u_k\}$  be a basis of a subspace  $V$ . How to transform  $\{u_1, u_2, \dots, u_k\}$  into an orthogonal basis  $\{v_1, v_2, \dots, v_k\}$ ?

**Gram-Schmidt  
Process**

Then  $\{v_1, v_2, \dots, v_k\}$  is an orthogonal basis for  $W$

Non-zero

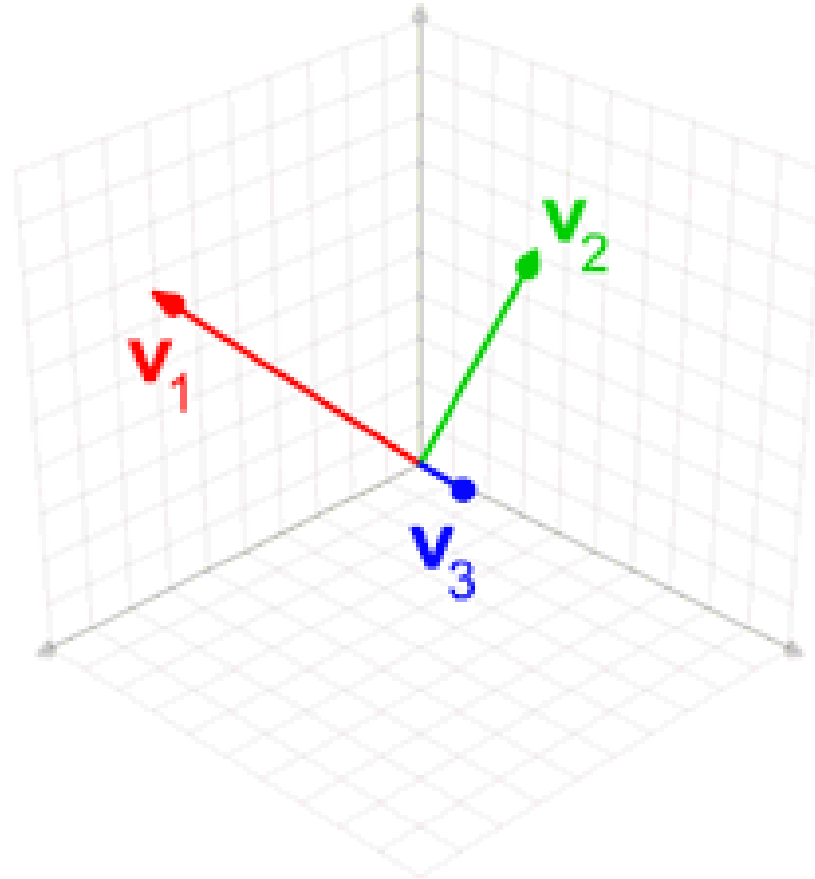


L.I.

$$\text{Span } \{v_1, v_2, \dots, v_i\} = \text{Span } \{u_1, u_2, \dots, u_i\}$$

orthogonal

# Visualization



<https://www.youtube.com/watch?v=Ys28-Yq21B8>

$$\mathbf{v}_1 = \mathbf{u}_1,$$

$$\mathbf{v}_2 = \mathbf{u}_2 - \frac{\mathbf{u}_2 \cdot \mathbf{v}_1}{\|\mathbf{v}_1\|^2} \mathbf{v}_1,$$

$$\mathbf{v}_3 = \mathbf{u}_3 - \frac{\mathbf{u}_3 \cdot \mathbf{v}_1}{\|\mathbf{v}_1\|^2} \mathbf{v}_1 - \frac{\mathbf{u}_3 \cdot \mathbf{v}_2}{\|\mathbf{v}_2\|^2} \mathbf{v}_2,$$

$\vdots$

$$\mathbf{v}_k = \mathbf{u}_k - \frac{\mathbf{u}_k \cdot \mathbf{v}_1}{\|\mathbf{v}_1\|^2} \mathbf{v}_1 - \frac{\mathbf{u}_k \cdot \mathbf{v}_2}{\|\mathbf{v}_2\|^2} \mathbf{v}_2 - \cdots - \frac{\mathbf{u}_k \cdot \mathbf{v}_{k-1}}{\|\mathbf{v}_{k-1}\|^2} \mathbf{v}_{k-1}$$

$\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$  be a basis of a subspace  $V$

$$\text{Span} \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_i\} = \text{Span} \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_i\}$$

Intuitive explanation

orthogonal

The theorem holds for  $k = 1$ . obviously

Assume the theorem holds for  $k=n$ , and consider the case for

$n+1$ .  $v_{n+1} \cdot v_i = 0$  ( $i < n + 1$ )

## Example

$\mathcal{S} = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  Is a basis for subspace  $W$

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \mathbf{u}_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \\ 1 \end{bmatrix} \quad \mathbf{u}_3 = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 1 \end{bmatrix} \quad (\text{L.I. vectors})$$

Then  $\mathcal{S}' = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is an orthogonal basis for  $W$ .

$\mathcal{S}'' = \{\mathbf{v}_1, \mathbf{v}_2, 4\mathbf{v}_3\}$  is also an orthogonal basis.

$$\mathbf{v}_1 = \mathbf{u}_1$$

$$\mathbf{v}_2 = \mathbf{u}_2 - \frac{\mathbf{u}_2 \cdot \mathbf{v}_1}{\|\mathbf{v}_1\|^2} \mathbf{v}_1,$$

$$\mathbf{v}_3 = \mathbf{u}_3 - \frac{\mathbf{u}_3 \cdot \mathbf{v}_1}{\|\mathbf{v}_1\|^2} \mathbf{v}_1 - \frac{\mathbf{u}_3 \cdot \mathbf{v}_2}{\|\mathbf{v}_2\|^2} \mathbf{v}_2$$

# Acknowledgement

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