

2.2 Differential PCM (DPCM)

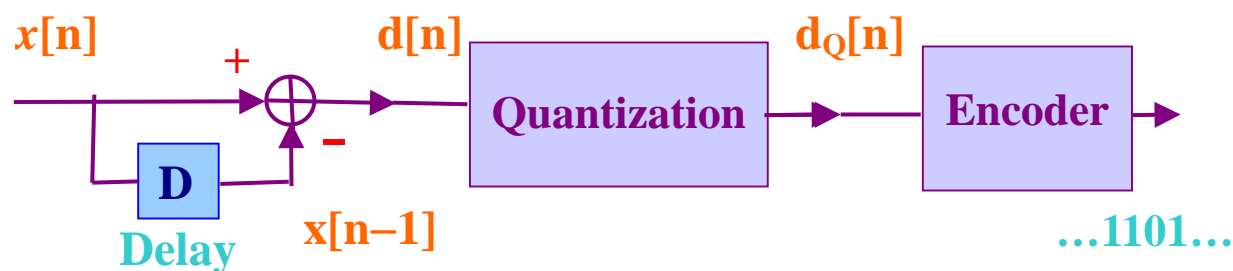
- Quantize and transmit only the differences in samples

$$d[n] = x[n] - x[n-1]$$

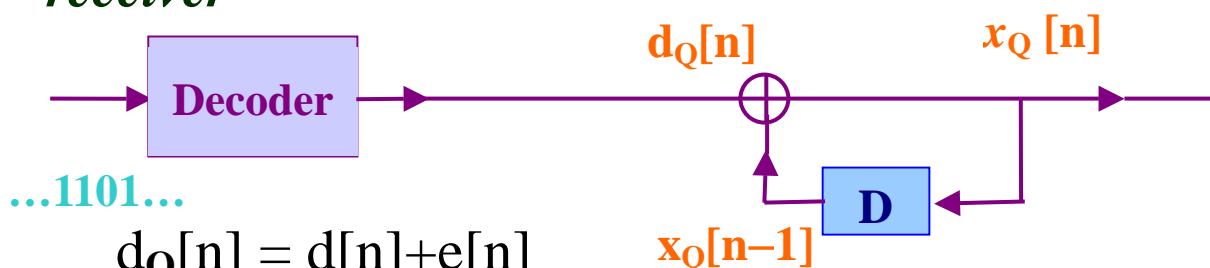
much smaller values of $d[n]$ give much better performance

Error Accumulation Problem

transmitter



receiver



$$d_Q[n] = d[n] + e[n]$$

$$x_Q[n] = x_Q[n-1] + d_Q[n]$$

$$= x_Q[n-1] + d[n] + e[n]$$

$$x_Q[n+1] = x_Q[n] + d_Q[n+1]$$

$$= x_Q[n-1] + d[n] + e[n] + d[n+1] + e[n+1]$$

↑ ↑
quantization error
accumulated

Error Accumulation Problem

- **Solution**

$$\begin{aligned} \text{redefine } d[n] &= x[n] - x_Q[n-1] \\ &= x[n] - (x_Q[n-2] + d[n-1] + e[n-1]) \end{aligned}$$

previous errors absorbed

See Fig. 3.28 , p. 228 of Haykin

use of very limited memory and computation

Processing Gain

$$\text{SNR}'_Q = \frac{\sigma_x^2}{\sigma_e^2} = \frac{\sigma_x^2}{\sigma_d^2} \cdot \frac{\sigma_d^2}{\sigma_e^2}$$

||
SNR_Q

$$G = \frac{\sigma_x^2}{\sigma_d^2}$$

$$\begin{aligned} \sigma_d^2 &= E[(d[n])^2] = E[(x[n] - x[n-1])^2] \\ &= E[(x[n])^2] + E[(x[n-1])^2] - 2E[(x[n]x[n-1])] \end{aligned}$$

$$\begin{aligned} \text{define } r_1 &= \frac{E[(x[n]x[n-1])]}{E[(x[n])^2]} \\ &= E[(x[n])^2] (2-2r_1) \\ &= \sigma_x^2 \cdot 2(1-r_1) \end{aligned}$$

$$G = \frac{1}{2(1-r_1)}$$

r_1 : varying for speech, audio signals, etc.
averaged over a short period only
note : $e[n]$ neglected here

Linear Prediction of Signals

- signal samples are highly correlated locally
- previous samples can be used to predict the next sample

• Formulation

$$\tilde{x}[n] = \sum_{k=1}^P w_k x[n-k]$$

P : prediction order

$$d[n] = x[n] - \tilde{x}[n]$$

See Fig. 3.26 , p. 223 of Haykin

$$\sigma_d^2 = E[(d[n])^2] = \min$$

$$\frac{\partial \sigma_d^2}{\partial w_k} = 0$$

Linear Prediction of Signals

- **Solution**

$$\overline{\mathbf{w}} = \mathbf{R}^{-1} \overline{\mathbf{r}}$$

$$\overline{\mathbf{w}} = [w_1, w_2, \dots, w_p]^t$$

$$\overline{\mathbf{r}} = [r_1, r_2, \dots, r_p]^t$$

$$\mathbf{R} = \begin{bmatrix} r_0 & r_1 & r_2 & \dots & r_{p-1} \\ r_1 & r_0 & r_1 & \dots & r_{p-2} \\ r_2 & r_1 & r_0 & \dots & r_{p-3} \\ \vdots & \vdots & \vdots & & \vdots \\ r_{p-1} & r_{p-2} & r_{p-3} & \dots & r_0 \end{bmatrix}$$

$$r_k = \frac{E[(x[n]x[n-k])]}{E[(x[n])^2]}$$

Wiener-Hopf Equation

Vector Space Interpretation of Wiener-Hopf Equation

- **3-dim Vector Space — an estimation problem**

Given $\bar{y}_1, \bar{y}_2, \bar{x}$, find

$\bar{x}^* = a_1\bar{y}_1 + a_2\bar{y}_2$, a best estimate of \bar{x}

such that $\|\bar{x} - \bar{x}^*\|^2 = [(\bar{x} - \bar{x}^*) \cdot (\bar{x} - \bar{x}^*)] = \min$

- Solution :

$$\begin{cases} (\bar{x} - a_1\bar{y}_1 - a_2\bar{y}_2) \cdot \bar{y}_1 = 0 \\ (\bar{x} - a_1\bar{y}_1 - a_2\bar{y}_2) \cdot \bar{y}_2 = 0 \end{cases}$$

- Orthogonality Principle : the difference vector should be orthogonal to the plane of (y_1, y_2) , or to both y_1 and y_2
- This principle can be extended to all vector space with valid definition of inner product

- **Vector Space of Random Variables**

$V = \{ X ; X \text{ is a random variable} \}$

- $X \cdot Y \equiv E[XY]$

$$\|X\| = E[X^2]$$

X is orthogonal to Y if $E[XY] = 0$

Vector Space Interpretation of Wiener-Hope Equation

- **Orthogonality Principle for Linear Prediction**

- Given $x[n-1]$, $x[n-2]$, ... $x[n-p]$ and $x[n]$, find

$$\tilde{x}[n] = \sum_{k=1}^P w_k x[n-k]$$

such that $\| x[n] - \tilde{x}[n] \|^2 = \min$

- Orthogonality Principle

$$(x[n] - \sum_{k=1}^P w_k x[n-k]) \cdot (x[n-j]) = 0 ,$$

$$j = 1, 2, 3, \dots, p$$

$$E[(x[n]x[n-j])] = \sum_{k=1}^P w_k E[(x[n-k])x[n-j]]$$

$$j = 1, 2, 3, \dots, p$$

$$\bar{r} = R \bar{w}$$

$$\bar{w} = R^{-1} \bar{r} \quad \text{Wiener-Hopf Equation}$$

Adaptive Linear Prediction

r_k in \bar{r} , R are time-varying

w_k are time-varying

$\hat{r}_k[n]$, $\hat{w}_k[n]$ estimated based on short-time statistics obtained with windowed $x[n]$

Improved DPCM with Linear Prediction

$$\tilde{x}[n] = \sum_{k=1}^P \hat{w}_k[n] x_Q[n-k]$$

$\hat{w}_k[n]$: estimate of w_k at time n

best estimate of $x[n]$ by minimizing σ_d^2

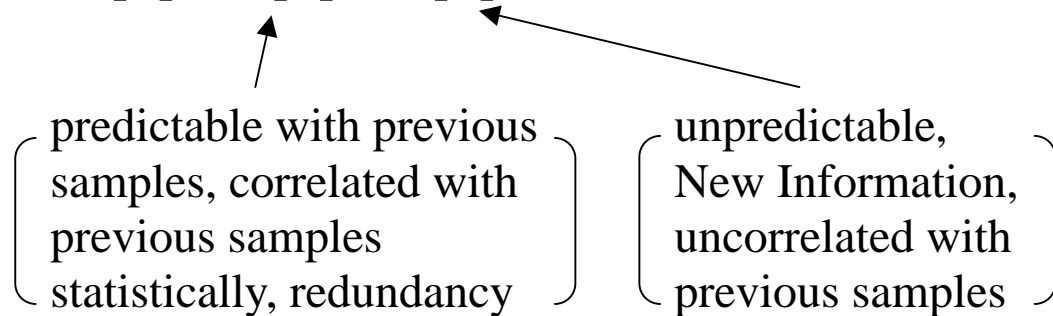
$$d[n] = x[n] - \tilde{x}[n]$$

See Fig. 3.28 , p. 228 of Haykin

$$\sigma_d^2 = \min, G = \max$$

• Redundancy and Predictability

$$x[n] = \tilde{x}[n] + d[n]$$



- DPCM is to remove the redundancy before quantization
- Using more computation and memory to improve performance