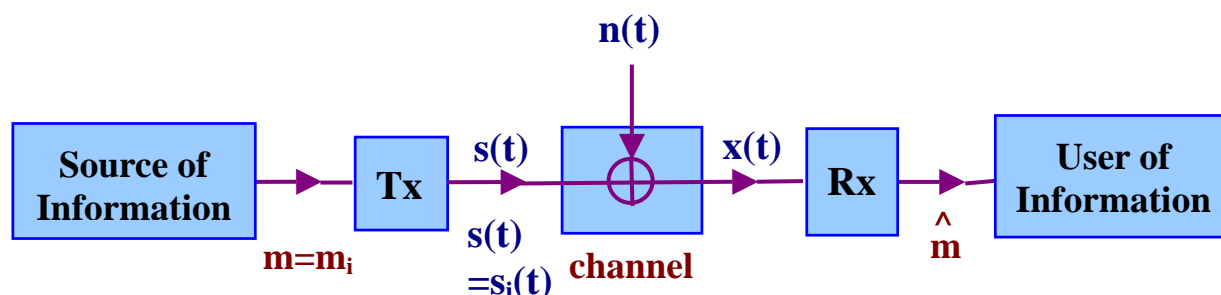


## 3.6 Vector Space Theory of Digital Communications

### Problem Definition



- **Source of Information**

a symbol  $m = m_i \in \{m_1, m_2, \dots, m_M\}$  sent at a time in  $[0, T]$

$$\text{Prob}[m = m_i] = P_i, \sum_{i=1}^M P_i = 1$$

- Example:  $M = 2$

$$m_1 = 1, m_2 = 0$$

$$M = 4$$

$$m_1 = 00, m_2 = 01, m_3 = 10, m_4 = 11$$

- **Transmitter**

a signal pulse  $s(t) = s_i(t) \in \{s_1(t), s_2(t), \dots, s_M(t)\}$  sent if  $m = m_i$ ,  $s_i(t)$  defined in  $[0, T]$

- **Channel**

ideal channel,  $x(t) = s(t) + n(t)$  in  $[0, T]$

$n(t)$  : white, Gaussian, zero-mean

$$S_n(\omega) = \frac{N_0}{2}, \text{ all } \omega$$

$$R_n(\tau) = \frac{N_0}{2} \delta(\tau)$$

## **Problem Definition**

- **Receiver**

a mapping relation

$$R_x : x(t) \rightarrow \hat{m} \in \{m_1, m_2, \dots, m_M\}$$

- **Symbol Error Probability**

$$P_{e,s} = \text{Prob}[\hat{m} \neq m] = \sum_{i=1}^M \text{Prob}[\hat{m} \neq m_i | m_i] P_i$$

- **Goal**

Design the mapping relation in Receiver such that

$$P_{e,s} = \min$$

## Vector Space Representation of the Problem

- **Assume a set of basis functions**

$$\{\phi_j(t), j = 1, 2, \dots, N\}$$

$$\int_0^T \phi_i(t) \phi_j(t) dt = \delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

- orthonormal basis

- **Assume the M signals  $\{s_i(t), i = 1, 2, \dots, M\}$  can be expanded from these N basis functions**

$$s_i(t) = \sum_{j=1}^N s_{ij} \phi_j(t)$$

$$s_{ij} = \int_0^T s_i(t) \phi_j(t) dt$$

$$= \int_0^T \left[ \sum_{k=1}^N s_{ik} \phi_k(t) \right] \phi_j(t) dt$$

$$s_i(t) \longleftrightarrow \bar{s}_i = (s_{i1}, s_{i2}, \dots, s_{iN})$$

$$[s_i(t)] \cdot [s_j(t)] = \int_0^T s_i(t) s_j(t) dt = \bar{s}_i \cdot \bar{s}_j = \sum s_{ik} s_{jk}$$

$$\int_0^T [s_i(t)]^2 dt = \|\bar{s}_i\|^2 = E_i$$

- **Dimension N of the sub-space**

$$N \leq M$$

- Gram-Schmidt Orthogonalization Procedure

$$\phi_1(t) = s_1(t) / E_1^{1/2}$$

$$a_{21} = \int_0^T s_2(t) \phi_1(t) dt$$

$$\phi_2'(t) = s_2(t) - a_{21} \phi_1(t)$$

$$E_2' = \int_0^T [\phi_2'(t)]^2 dt$$

$$\phi_2(t) = \phi_2'(t) / (E_2')^{1/2}, \dots\dots$$

- M signals expand an N-dim subspace,  $N \leq M$

## Vector Space Representation of the Problem

- **Projection of  $n(t)$  in the N-dim subspace**

$$n(t) \rightarrow \bar{n} = (n_1, n_2, \dots, n_N)$$

$$n_j = \int_0^T n(t) \phi_j(t) dt$$

$$n(t) = \sum_{j=1}^N n_j \phi_j(t) + n'(t)$$

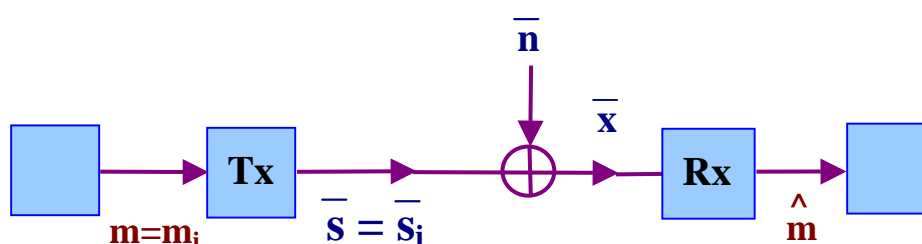
$\uparrow$   
 noise outside of the subspace or  
 orthogonal to the subspace

- **Thm :**

$n'(t)$  is Irrelevant for optimal decision

optimal decision can be made solely in the subspace without considering  $n'(t)$

- **Vector Space Representation**



$$\bar{x} = \bar{s} + \bar{n}$$

$$R_x : \bar{x} \rightarrow \hat{m} \in \{m_1, m_2, \dots, m_M\}$$

$x(t)$  reduced to a N-dim vector,  $N \leq M$

## Vector Space Representation of the Problem

### Statistics of $\bar{\mathbf{n}}$

$$n_j = \int_0^T n(t) \phi_j(t) dt$$

$n_j$  : Gaussian, zero-mean random variable

$$\begin{aligned} E[n_i n_j] &= E\left[\int_0^T n(t) \phi_i(t) dt \int_0^T n(\tau) \phi_j(\tau) d\tau\right] \\ &= \iint_0^T \phi_i(t) \phi_j(\tau) E[n(t) n(\tau)] dt d\tau \\ &\quad \uparrow \\ &\quad R_n(t-\tau) = \frac{N_0}{2} \delta(t-\tau) \\ &= \frac{N_0}{2} \delta_{ij} = \begin{cases} \frac{N_0}{2}, & i = j \\ 0, & i \neq j \end{cases} \end{aligned}$$

- all  $n_j$  are independent, identically distributed (iid), Gaussian, zero-mean with variance  $\sigma^2 = \frac{N_0}{2}$

$$f_{n_j}(n) = \frac{1}{(2\pi)^{1/2} \sigma} e^{-n^2/2\sigma^2}$$

$$f_{\bar{\mathbf{n}}}(\bar{\mathbf{n}}) = \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-|\bar{\mathbf{n}}|^2/2\sigma^2}$$

spherically symmetry, isotropic

*See Fig. 5.4, 5.7, p. 313, p. 323 of Haykin*

## Optimal Decision

### • Maximum A Posteriori Probability (MAP) Principle

assume  $\bar{x}$  is received

possibly  $m_1$  was sent with  $\text{Prob}[m_1 | \bar{x}]$

$m_2$  was sent with  $\text{Prob}[m_2 | \bar{x}]$

$\vdots$

$m_k$  was sent with  $\text{Prob}[m_k | \bar{x}] = \max$

$\vdots$

$m_M$  was sent with  $\text{Prob}[m_M | \bar{x}]$

if  $\text{Prob}[m_k | \bar{x}] > \text{Prob}[m_j | \bar{x}]$ ,  $j \neq k$

then let  $\bar{x} \rightarrow \hat{m} = m_k$

### • Evaluation of $\text{Prob}[m_i | \bar{x}]$

$$\text{Prob}[m_i | \bar{x}] = \frac{\text{Prob}[\bar{x} | m_i] P_i}{\text{Prob}[\bar{x}]} = D_i(\bar{x}), \text{ decision function}$$

$R_X: \bar{x} \rightarrow \hat{m} = m_k$  if  $D_k(\bar{x}) = \max$  among all  $D_i(\bar{x})$

$$D_i(\bar{x}) = \text{Prob}[\bar{x} | m_i] P_i = \text{Prob}[\bar{x} | \bar{s}_i] P_i$$

$$= \text{Prob}[\bar{n} = \bar{x} - \bar{s}_i] P_i$$

$$= f_{\bar{n}}(\bar{x} - \bar{s}_i) P_i$$

$$= \left[ \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-|\bar{x} - \bar{s}_i|^2 / 2\sigma^2} \right] \cdot P_i$$

$$D_i(\bar{x}) = -|\bar{x} - \bar{s}_i|^2 + 2\sigma^2 \ln[P_i]$$

- assign  $\hat{m}$  to the signal vector NEAREST to  $\bar{x}$ , with distance adjusted by  $P_i$
- most probable noise corresponds to minimum distance

## Optimal Decision

### • Decision Region

the N-dim subspace can be divided into M regions in advance,  $R_i = \{\bar{x} | \bar{x} \rightarrow m_i\}$ ,  $i = 1, 2, \dots, M$

- boundary between  $R_i$  and  $R_j$  defined by

$$D_i(\bar{x}) = D_j(\bar{x})$$

## Receiver Structure

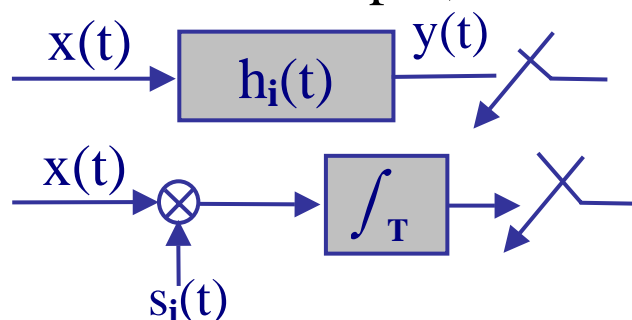
$$\begin{aligned} D_i(\bar{x}) &= -|\bar{x} - \bar{s}_i|^2 + 2\sigma^2 \ln[P_i] \\ &= -|\bar{x}|^2 - |\bar{s}_i|^2 + 2\bar{x} \cdot \bar{s}_i + 2\sigma^2 \ln[P_i] \\ D_i(\bar{x}) &= \bar{x} \cdot \bar{s}_i + \sigma^2 \ln[P_i] - \frac{1}{2} |\bar{s}_i|^2 \\ &= \bar{x} \cdot \bar{s}_i + C_i \end{aligned}$$

### • Receiver Structure 1

$$\bar{x} \cdot \bar{s}_i = \int_0^T x(t) s_i(t) dt = y(t_1)$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h_i(t-\tau) d\tau, \quad h_i(t) = s_i(t_1-t)$$

- matched filter output, correlator



- a total of M arms needed in general

### • Receiver Structure 2

$$\begin{aligned} \bar{x} &= (x_1, x_2, \dots, x_N), \quad \bar{x} \cdot \bar{s}_i = \sum_{j=1}^N x_j s_{ij} \\ x_j &= \int_0^T x(t) \phi_j(t) dt, \quad j = 1, 2, \dots, N \end{aligned}$$

- a total of N arms needed, useful when  $N < M$

See Fig. 5.9, p. 327 of Haykin

## Error Probability Independent of Choice of Basis

- Decision Regions  $\{R_i, i = 1, 2, \dots, M\}$  independent of basis
- Error probabilities depends on the constellation structure and distances among the signal vectors only
- $\bar{n}$  is spherically symmetric

examples :  $N = 2, M = 2$

$N = 2, M = 4$

### • Minimum Energy Signal Set

Given  $\{\bar{s}_i, i = 1, 2, \dots, M\}$ , find  $\bar{a}$  such that

$$\sum_{i=1}^M \|\bar{s}_i - \bar{a}\|^2 P_i = \min$$

$$\bar{a} = \sum_{i=1}^M \bar{s}_i P_i$$

*Ref : 5.1, 5.2, 5.3, 5.4, 5.5, 5.6, 5.7 of Haykin*