

Basis

Hung-yi Lee

# Outline

- What is a basis for a subspace?
- Confirming that a set is a basis for a subspace
- Reference: Textbook 4.2

What is Basis?

# Basis

Why nonzero?

- Let  $V$  be a nonzero subspace of  $\mathcal{R}^n$ . A **basis**  $B$  for  $V$  is a **linearly independent generation set** of  $V$ .

$\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$  is a basis for  $\mathcal{R}^n$ .

1.  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$  is independent
2.  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_n\}$  generates  $\mathcal{R}^n$ .

$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$  is a basis for  $\mathcal{R}^2$

$\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$   $\left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right\}$   $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$  ..... any two independent vectors form a basis for  $\mathcal{R}^2$

# Basis

- The pivot columns of a matrix form a basis for its columns space.

$$\begin{bmatrix} \boxed{1} & 2 & \boxed{-1} & \boxed{2} & 1 & 2 \\ \boxed{-1} & -2 & \boxed{1} & \boxed{2} & 3 & 6 \\ 2 & 4 & -3 & 2 & 0 & 3 \\ \boxed{-3} & -6 & \boxed{2} & \boxed{0} & 3 & 9 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 2 & \boxed{0} & \boxed{0} & -1 & -5 \\ \boxed{0} & 0 & \boxed{1} & \boxed{0} & 0 & -3 \\ \boxed{0} & 0 & \boxed{0} & \boxed{1} & 1 & 2 \\ \boxed{0} & 0 & \boxed{0} & \boxed{0} & 0 & 0 \end{bmatrix}$$

pivot columns

$$\text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \right\}$$

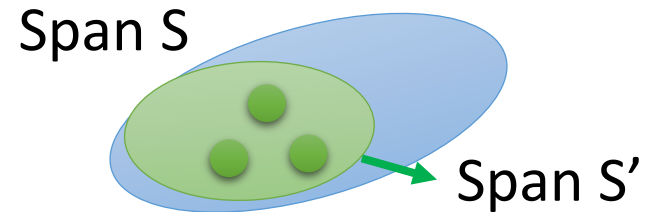
# Property

- (a)  $S$  is contained in  $\text{Span } S$

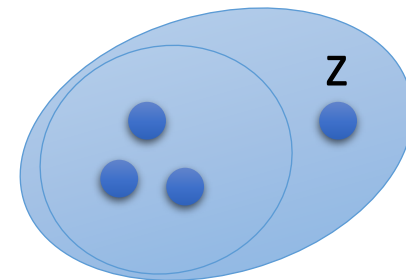
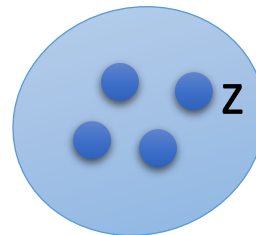
Basis is always in its subspace

- (b) If a finite set  $S'$  is contained in  $\text{Span } S$ , then  $\text{Span } S'$  is also contained in  $\text{Span } S$

- Because  $\text{Span } S$  is a subspace



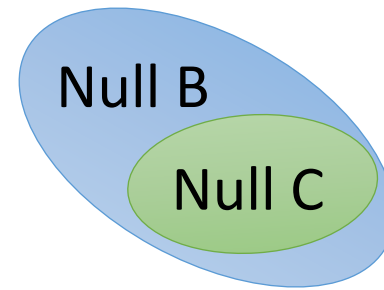
- (c) For any vector  $z$ ,  $\text{Span } S = \text{Span } S \cup \{z\}$  if and only if  $z$  belongs to the  $\text{Span } S$



# Theorem

- 1. A basis is the **smallest** generation set.
- 2. A basis is the **largest** independent vector set in the subspace.
- 3. Any two bases for a subspace **contain the same number of vectors**.
  - The number of vectors in a basis for a nonzero subspace  $V$  is called **dimension** of  $V$  ( $\dim V$ ).

# Theorem 3



- Any two bases of a subspace  $V$  contain the same number of vectors

Suppose  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$  and  $\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_p\}$  are two bases of  $V$ .

Let  $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_k]$  and  $B = [\mathbf{w}_1 \ \mathbf{w}_2 \ \cdots \ \mathbf{w}_p]$ .

Since  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$  spans  $V$ ,  $\exists \mathbf{c}_i \in \mathcal{R}^k$  s.t.  $A\mathbf{c}_i = \mathbf{w}_i$  for all  $i$

$$\Rightarrow A[\mathbf{c}_1 \ \mathbf{c}_2 \ \cdots \ \mathbf{c}_p] = [\mathbf{w}_1 \ \mathbf{w}_2 \ \cdots \ \mathbf{w}_p] \Rightarrow AC = B$$

$$\text{Now } C\mathbf{x} = \mathbf{0} \text{ for some } \mathbf{x} \in \mathcal{R}^p \Rightarrow AC\mathbf{x} = B\mathbf{x} = \mathbf{0}$$

$B$  is independent vector set  $\Rightarrow \mathbf{x} = \mathbf{0} \Rightarrow \mathbf{c}_1 \ \mathbf{c}_2 \ \cdots \ \mathbf{c}_p$  are independent

$$\mathbf{c}_i \in \mathcal{R}^k \Rightarrow p \leq k$$

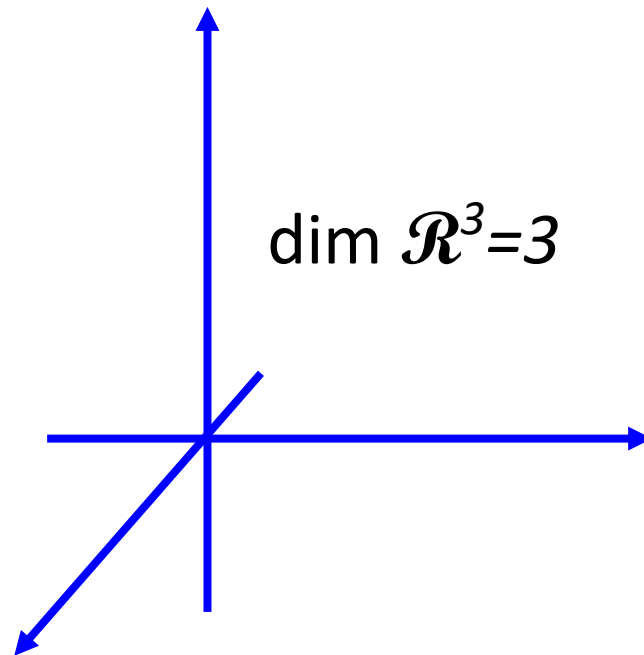
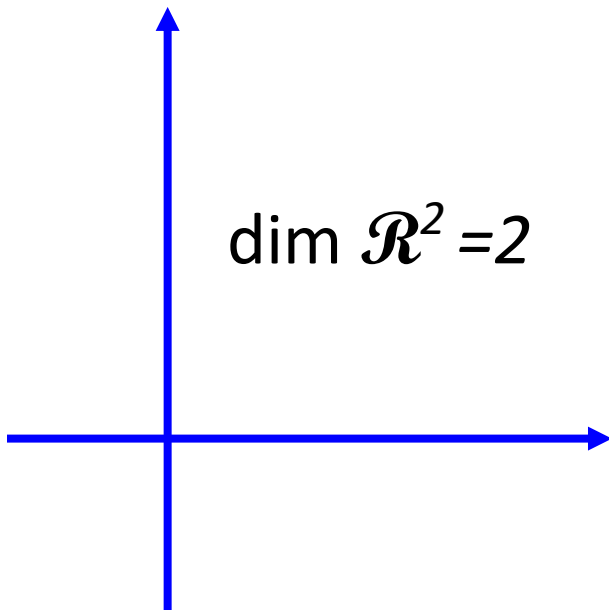
Reversing the roles of the two bases one has  $k \leq p \Rightarrow p = k$ .



# Theorem 3

Every basis of  $\mathcal{R}^n$   
has  $n$  vectors.

- The number of vectors in a basis for a subspace  $V$  is called the dimension of  $V$ , and is denoted  $\dim V$ 
  - The dimension of zero subspace is 0



# Example

$$V = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \in \mathcal{R}^4 : \begin{array}{l} \cancel{x_1 - 3x_2 + 5x_3 - 6x_4 = 0} \\ x_1 = 3x_2 - 5x_3 + 6x_4 \end{array} \right\} \quad \begin{array}{l} \text{Find dim } V \\ \text{dim } V = 3 \end{array}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 3x_2 - 5x_3 + 6x_4 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Basis? Independent vector set that generates  $V$



# Theorem 1

A basis is the smallest generation set.

If there is a generation set  $S$  for subspace  $V$ ,

The size of basis for  $V$  is smaller than or equal to  $S$ .

## Reduction Theorem

There is a basis containing in any generation set  $S$ .

$S$  can be reduced to a basis for  $V$  by removing some vectors.

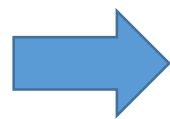
# Theorem 1 – Reduction Theorem

所有的 generation set 心中都有一個 basis

$S$  can be reduced to a basis for  $V$  by removing some vectors.

Suppose  $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$  is a generation set of subspace  $V$

Subspace  $V = \text{Span } S$       Let  $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \cdots \ \mathbf{u}_k]$ .  
 $= \text{Col } A$



The basis of  $\text{Col } A$  is the **pivot columns of  $A$**  Subset of  $S$

# Theorem 1 – Reduction Theorem

所有的 generation set 心中都有一個 basis

$$\text{Subspace } V = \text{Span } S = \text{Col } A = \text{Span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \right\}$$

Smallest generation set

$$S = \left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 4 \\ 6 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 6 \\ 3 \\ 9 \end{bmatrix} \right\}$$

Generation set

$$A = \begin{bmatrix} 1 & 2 & -1 & 2 & 1 & 2 \\ -1 & -2 & 1 & 2 & 3 & 6 \\ 2 & 4 & -3 & 2 & 0 & 3 \\ -3 & -6 & 2 & 0 & 3 & 9 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 2 & 0 & 0 & -1 & -5 \\ 0 & 0 & 1 & 0 & 0 & -3 \\ 0 & 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

# Theorem 2

A basis is the largest independent set in the subspace.

If the size of basis is  $k$ , then you cannot find more than  $k$  *independent* vectors in the subspace.

## *Extension Theorem*

Given an independent vector set  $S$  in the space

$S$  can be extended to a basis by adding more vectors

# Theorem 2 – Extension Theorem

Independent set:

我不是一個 basis 就是正在成為一個 basis

There is a subspace  $V$

Given a independent vector set  $S$  (elements of  $S$  are in  $V$ )

{ If  $\text{Span } S = V$ , then  $S$  is a basis

{ If  $\text{Span } S \neq V$ , find  $v_1$  in  $V$ , but not in  $\text{Span } S$

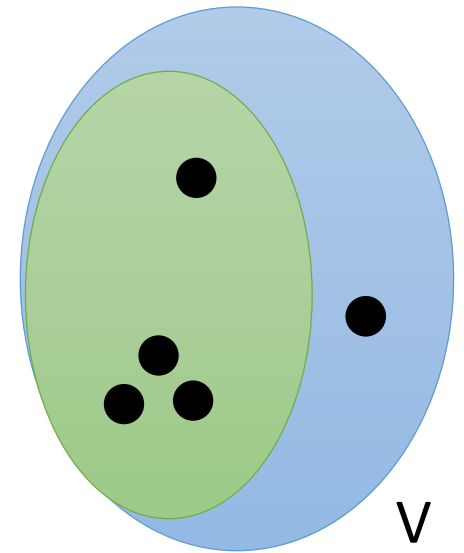
$S = S \cup \{v_1\}$  is still an independent set

{ If  $\text{Span } S = V$ , then  $S$  is a basis

{ If  $\text{Span } S \neq V$ , find  $v_2$  in  $V$ , but not in  $\text{Span } S$

$S = S \cup \{v_2\}$  is still an independent set

..... You will find the basis in the end.



# More from Theorems

A basis is the smallest generation set.

A vector set generates  $\mathcal{R}^m$  must contain at least  $m$  vectors.

$\mathcal{R}^m$  have a basis  $\{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_m\}$

Because a basis is the smallest generation set

Any other generation set has at least  $m$  vectors.

A basis is the largest independent set in the subspace.

Any independent vector set in  $\mathcal{R}^m$  contain at most  $m$  vectors.



# Summary

雕塑 ... 主要是使用雕（通過減除材料來造型）及塑（通過疊加材料來造型）的方式 ..... (from wiki)



Generation set

刪去



Same size



Basis

疊加



Independent vector set

Confirming that  
a set is a Basis

# Intuitive Way

- Definition: A **basis**  $B$  for  $V$  is an independent generation set of  $V$ .

$$V = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \in \mathcal{R}^3 : v_1 - v_2 + 2v_3 = 0 \right\} \quad \mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Is  $\mathcal{C}$  a basis of  $V$ ?

Independent? **yes**

Generation set? **difficult**

$$\mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\} \text{ generates } V$$

# Another way

Find a basis for  $V$

- Given a subspace  $V$ , assume that we already know that  $\dim V = k$ . Suppose  $S$  is a subset of  $V$  with  $k$  vectors

If  $S$  is independent  $\longrightarrow$   $S$  is basis

If  $S$  is a generation set  $\longrightarrow$   $S$  is basis

$$V = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \in \mathcal{R}^3 : v_1 - v_2 + 2v_3 = 0 \right\} \quad \mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$\dim V = 2$  (parametric representation)

Is  $\mathcal{C}$  a basis of  $V$ ?

$\mathcal{C}$  is a subset of  $V$  with 2 vectors  
Independent? **yes**  $\longrightarrow$   $\mathcal{C}$  is a basis of  $V$

# Another way

Assume that  $\dim V = k$ . Suppose  
 $S$  is a subset of  $V$  with  $k$  vectors

If  $S$  is independent   $S$  is basis

By the extension theorem, we can add more vector into  $S$  to form a basis.

However,  $S$  already have  $k$  vectors, so it is already a basis.

If  $S$  is a generation set   $S$  is basis

By the reduction theorem, we can remove some vector from  $S$  to form a basis.

However,  $S$  already have  $k$  vectors, so it is already a basis.

# Example

- Is  $\mathcal{B}$  a basis of  $V$ ?

$$V = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \in \mathcal{R}^4 : v_1 + v_2 + v_4 = 0 \right\} \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ -1 \end{bmatrix} \right\}$$

Independent set in  $V$ ? **yes**

Dim  $V = ?$  3   $\mathcal{B}$  is a basis of  $V$ .

# Example

- Is  $\mathcal{B}$  a basis of  $V = \text{Span } \mathcal{S}$ ?

$\mathcal{B}$  is a subset of  $V$  with 3 vectors

$$\mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \right\} \quad \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$$A = \begin{bmatrix} 1 & -1 & 3 & 1 \\ 1 & 3 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 2 & -1 & 1 & -1 \end{bmatrix} \xrightarrow{\text{blue arrow}} R_A = \begin{bmatrix} 1 & 0 & 0 & -2/3 \\ 0 & 1 & 0 & 1/3 \\ 0 & 0 & 1 & 2/3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{dim} A = 3$$

$$B = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{\text{blue arrow}} R_B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{Independent} \xrightarrow{\text{blue arrow}} \mathcal{B} \text{ is a basis of } V.$$