

Gated RNN & Sequence Generation

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Outline

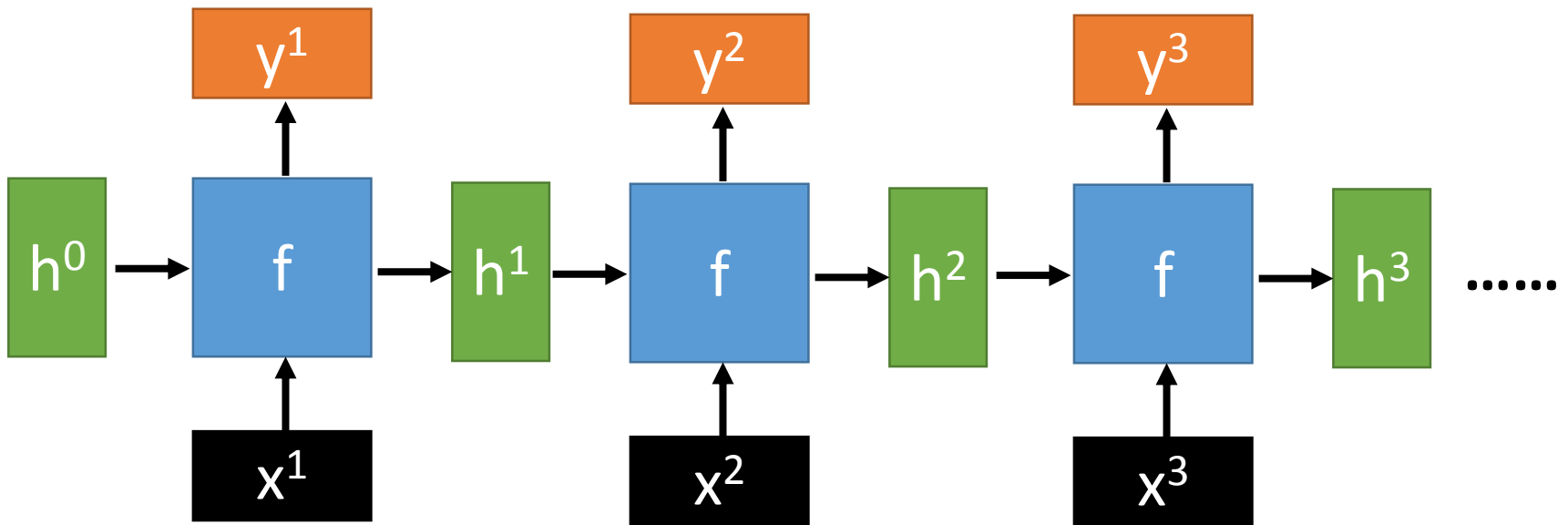
- RNN with Gated Mechanism
- Sequence Generation
- Conditional Sequence Generation
- Tips for Generation

RNN with Gated Mechanism

Recurrent Neural Network

- Given function $f: h', y = f(h, x)$

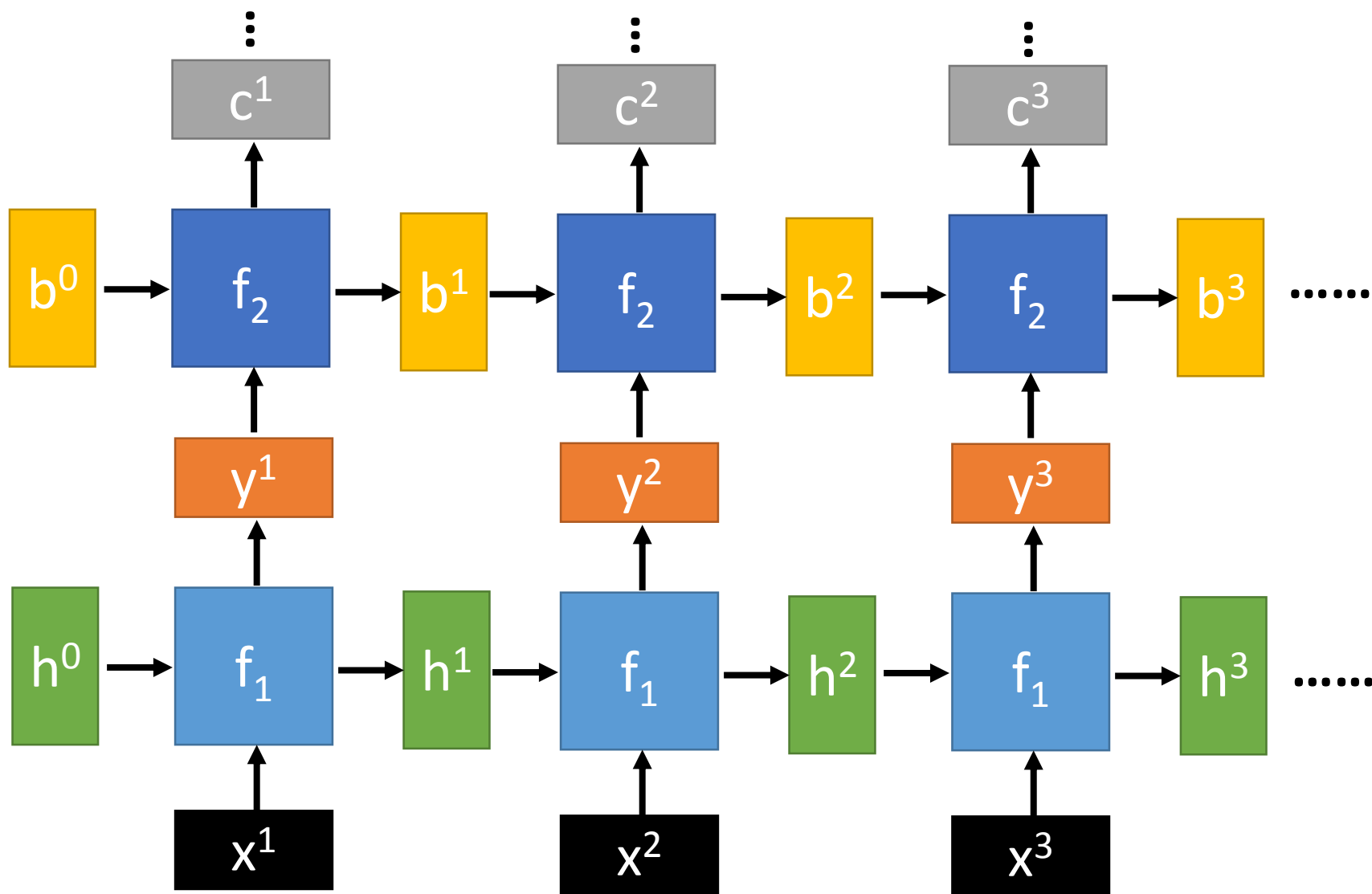
h and h' are vectors with the same dimension



No matter how long the input/output sequence is, we only need one function f

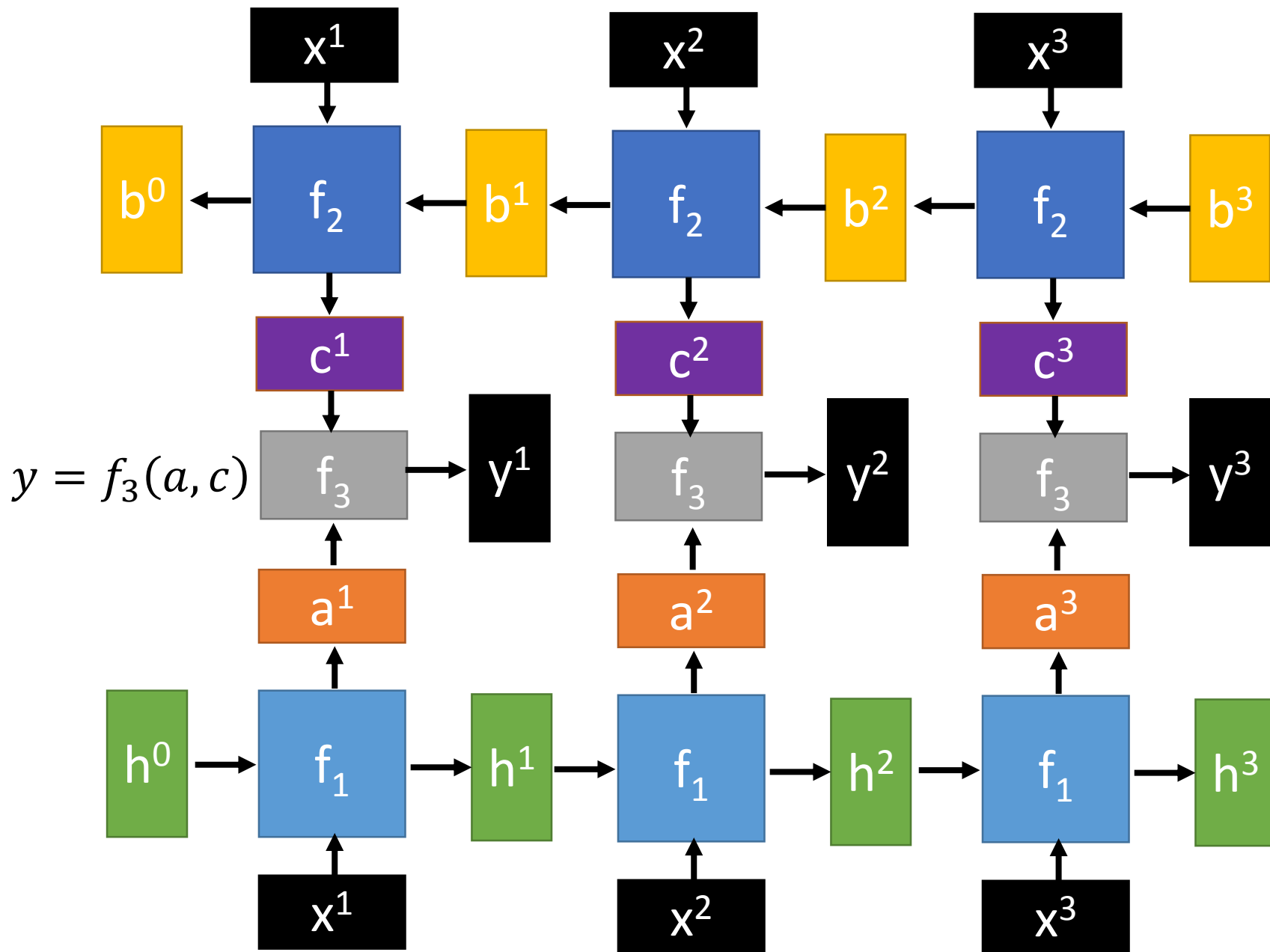
Deep RNN

$$h', y = f_1(h, x) \quad b', c = f_2(b, y) \dots$$



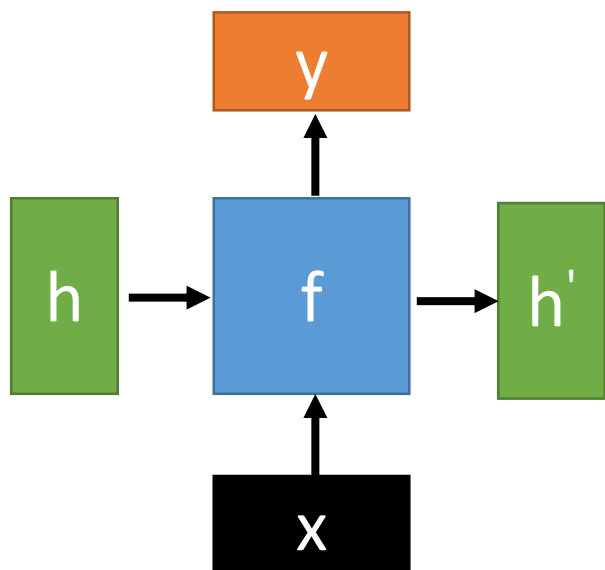
Bidirectional RNN

$$h', a = f_1(h, x) \quad b', c = f_2(b, x)$$



Naïve RNN

- Given function $f: h', y = f(h, x)$



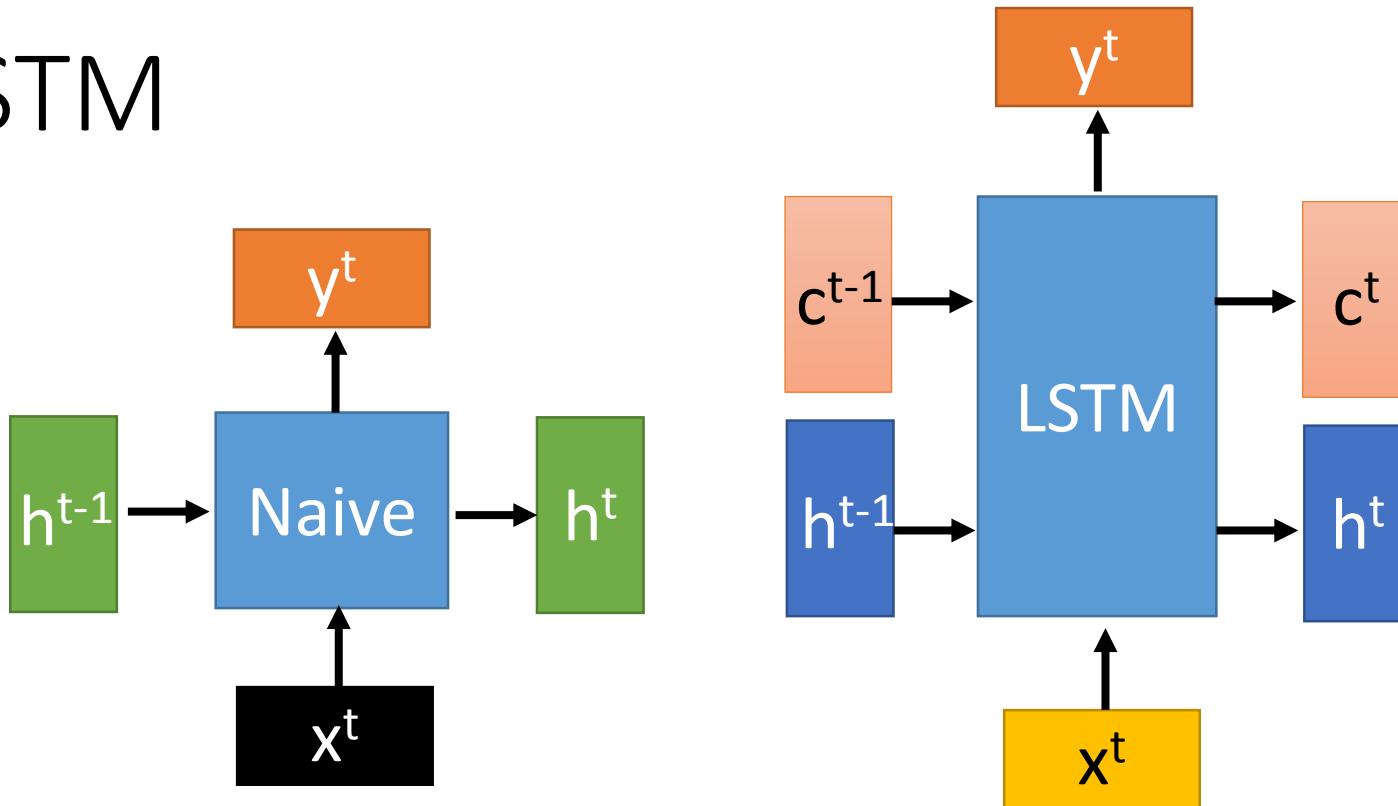
$$h' = \sigma(W^h h + W^i x)$$

$$y = \sigma(W^o h')$$

softmax

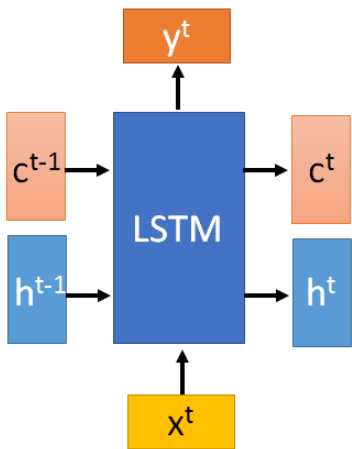
Ignore bias here

LSTM

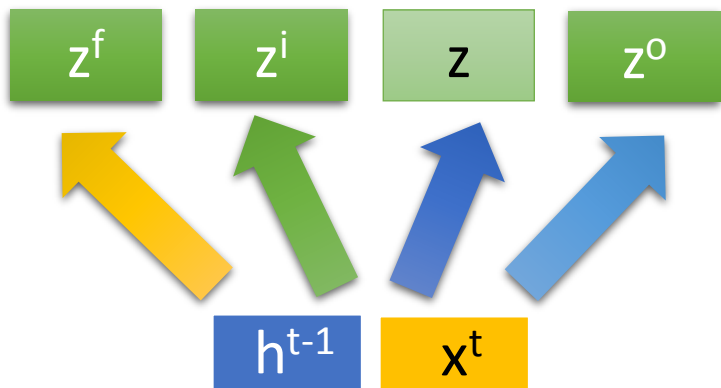


c changes slowly $\Rightarrow c^t$ is c^{t-1} added by something

h changes faster $\Rightarrow h^t$ and h^{t-1} can be very different



c^{t-1}



$$z = \tanh\left(W \begin{bmatrix} x^t \\ h^{t-1} \end{bmatrix} \right)$$

$$z^i = \sigma\left(W^i \begin{bmatrix} x^t \\ h^{t-1} \end{bmatrix} \right)$$

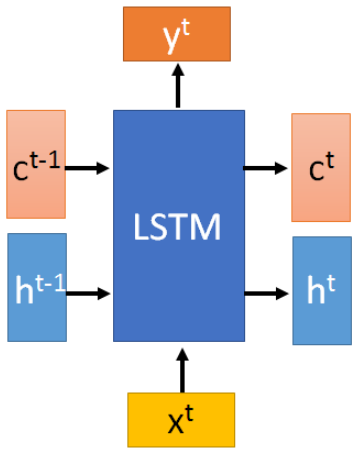
Input gate

$$z^f = \sigma\left(W^f \begin{bmatrix} x^t \\ h^{t-1} \end{bmatrix} \right)$$

forget gate

$$z^o = \sigma\left(W^o \begin{bmatrix} x^t \\ h^{t-1} \end{bmatrix} \right)$$

output gate

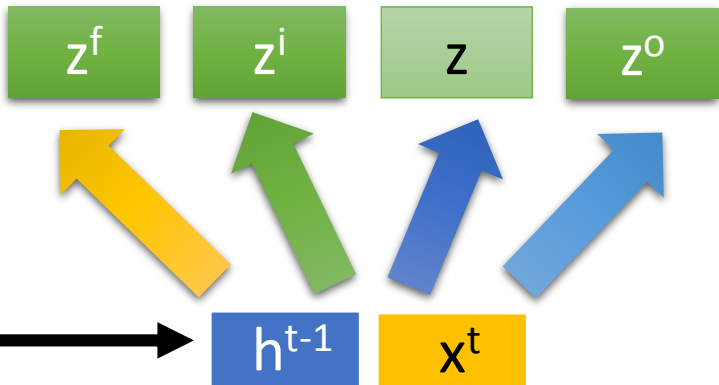


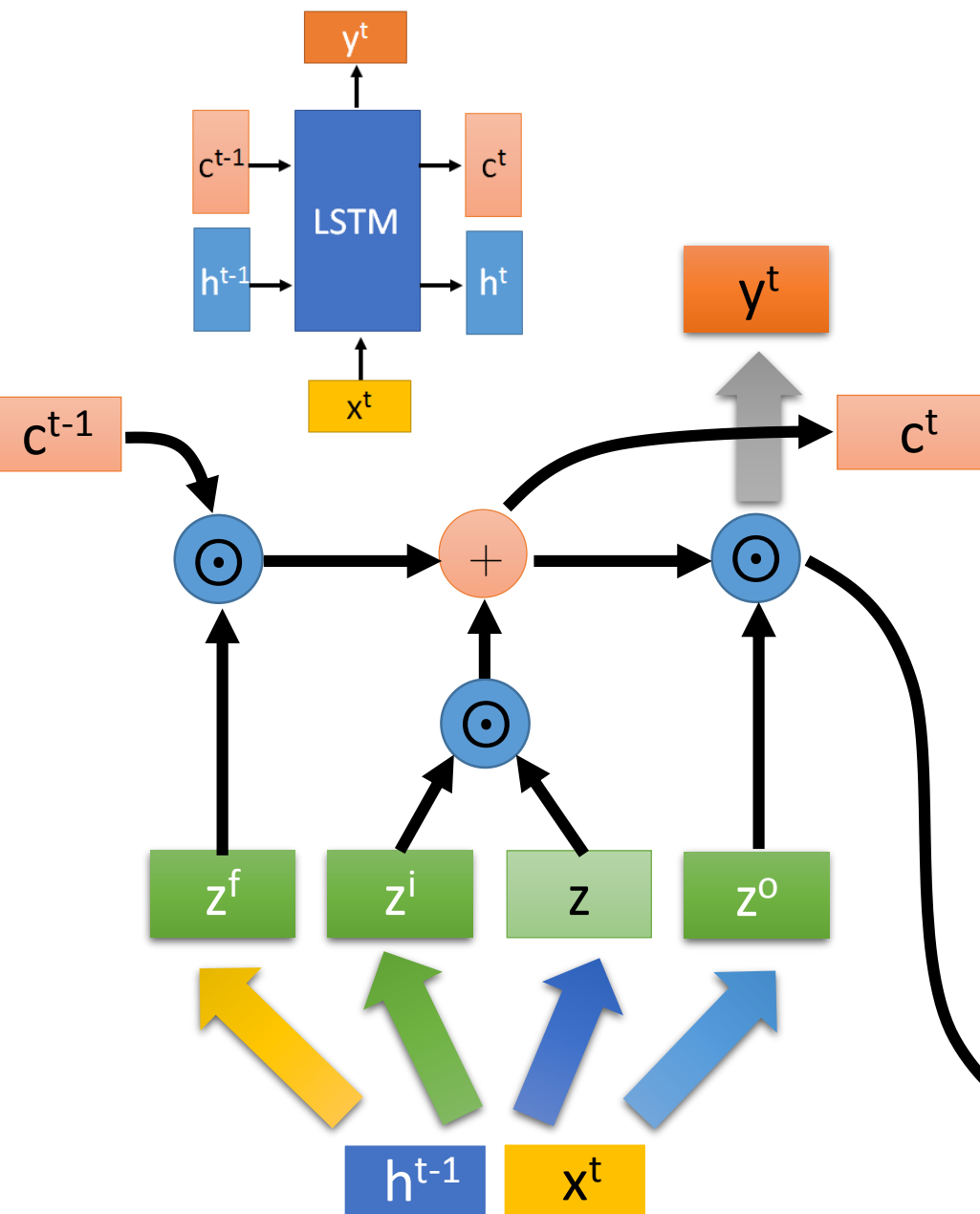
$$z = \tanh\left(\begin{matrix} \text{blue box } W & \text{orange box} \\ \text{orange box } c^{t-1} & \text{blue box } h^{t-1} \end{matrix} \right)$$

↑
diagonal

z^0 z^f z^i obtained by the same way

“peephole”



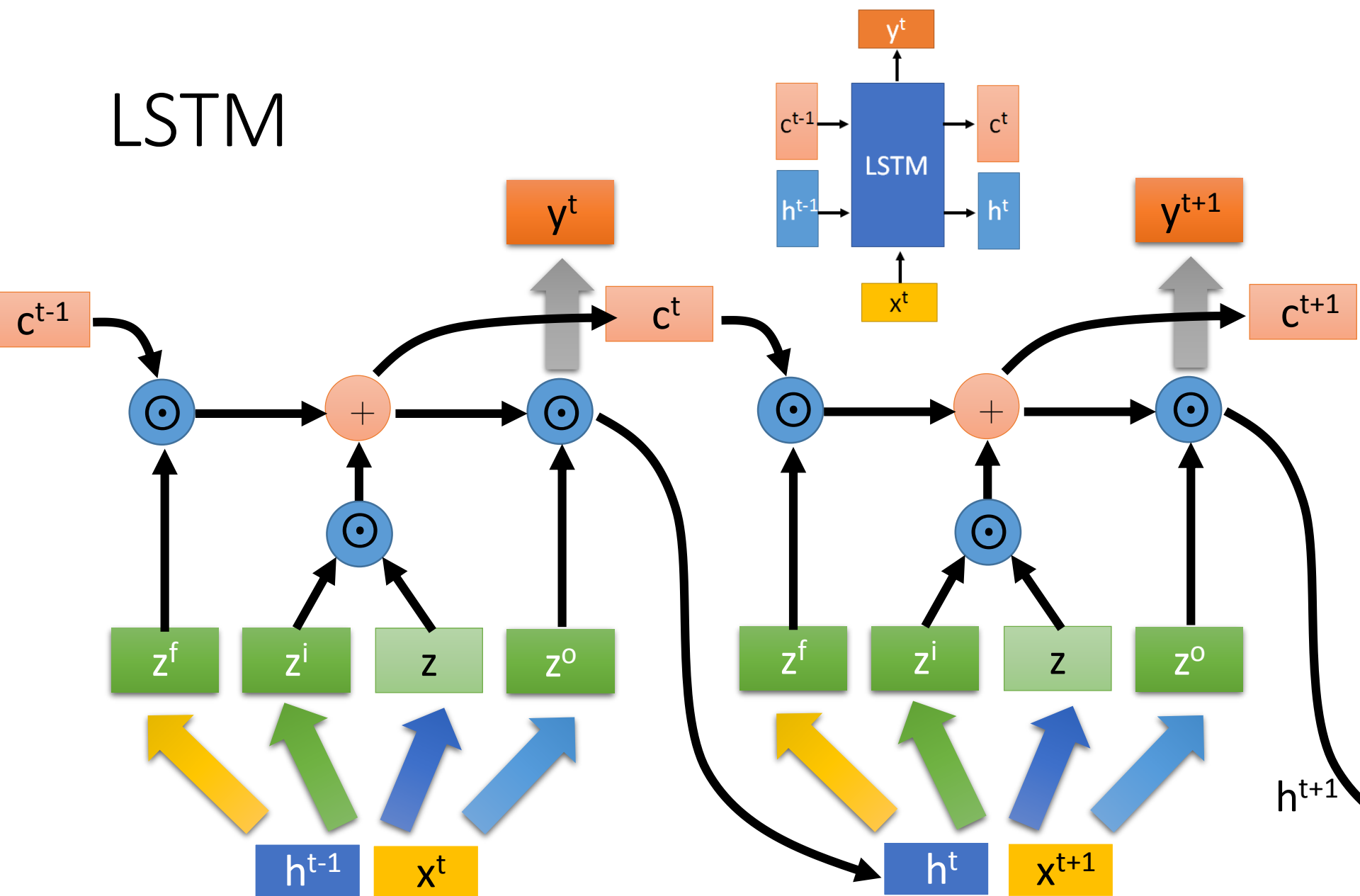


$$c^t = z^f \odot c^{t-1} + z^i \odot z$$

$$h^t = z^o \odot \tanh(c^t)$$

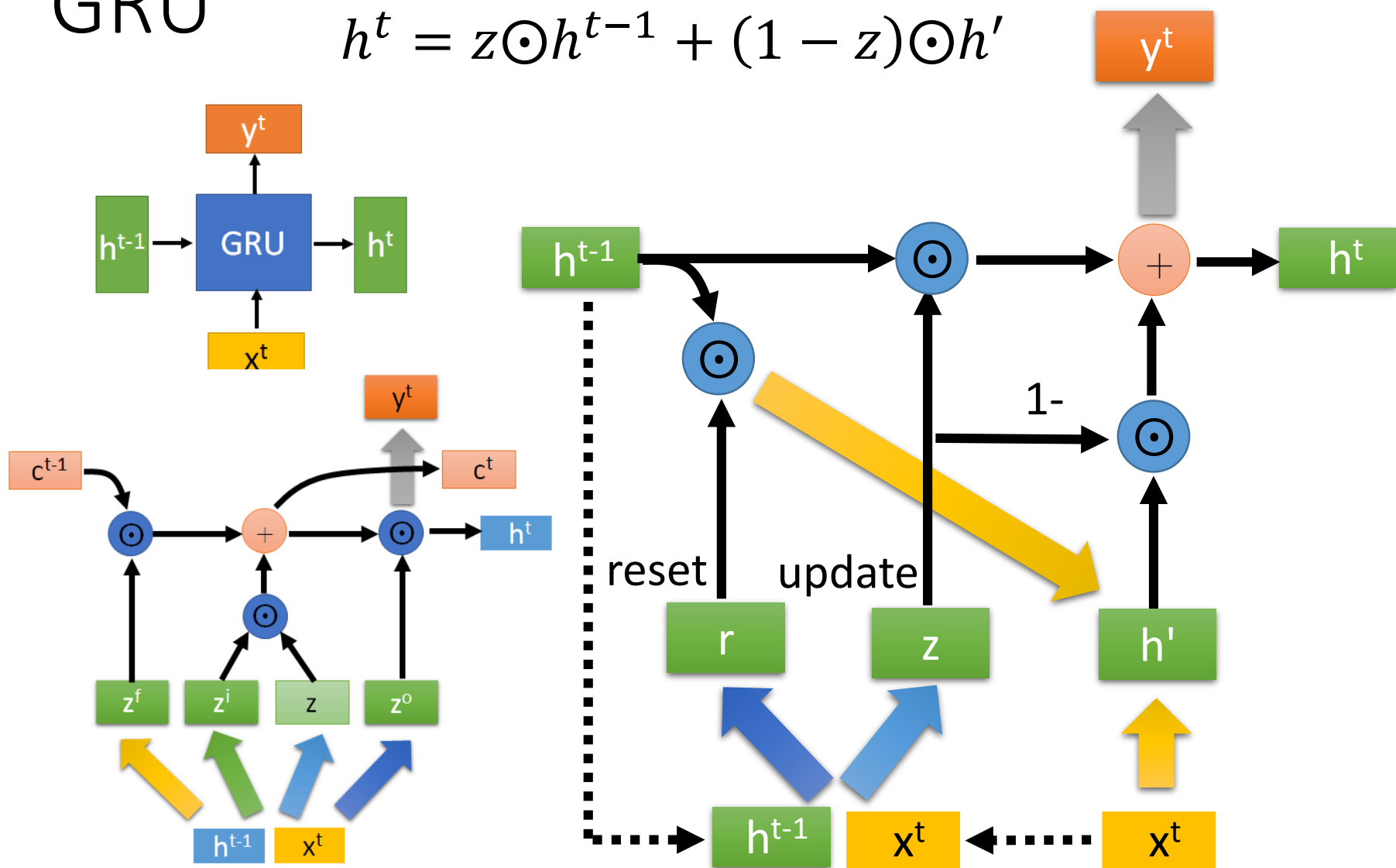
$$y^t = \sigma(W' h^t)$$

LSTM

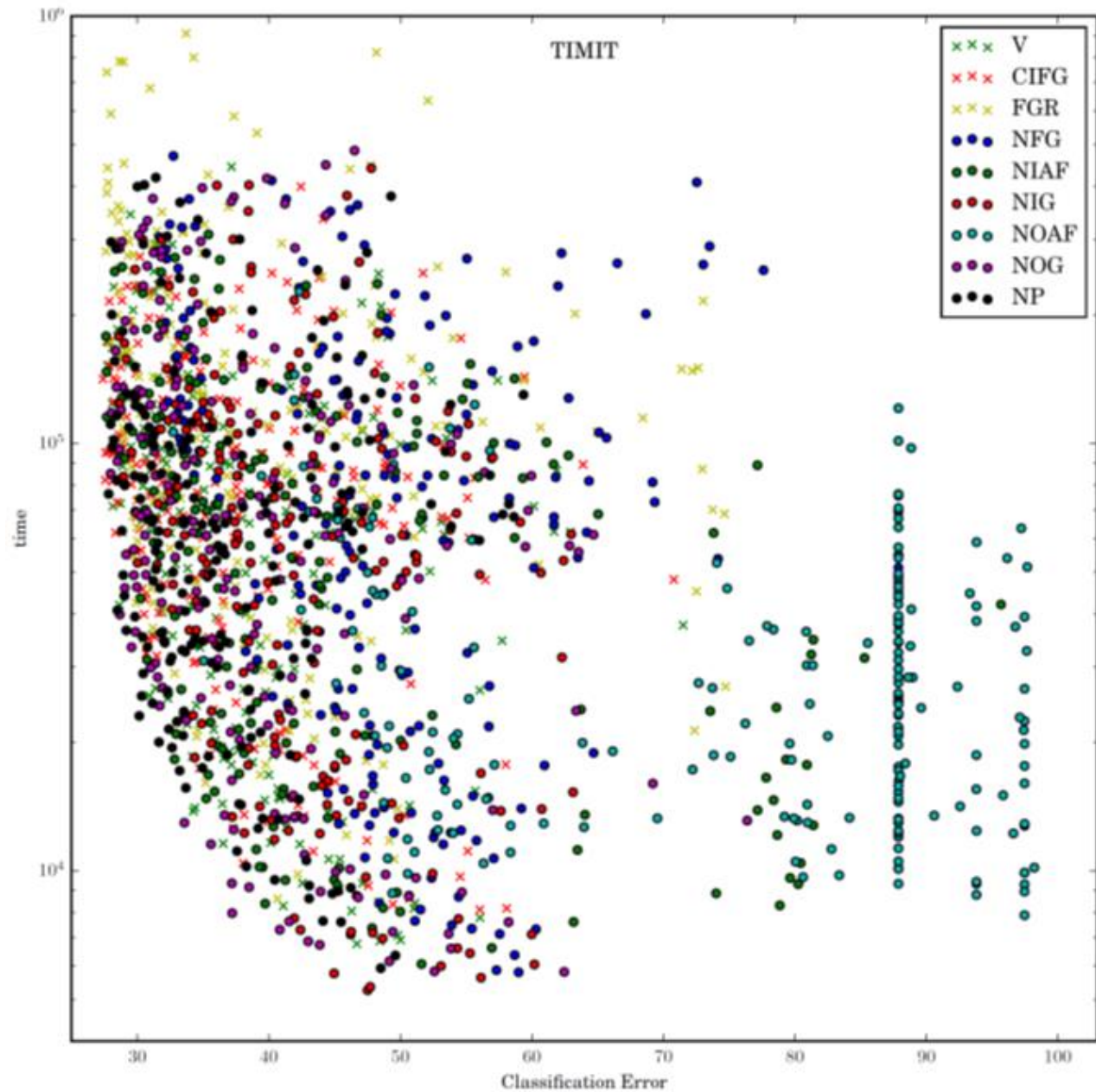


GRU

$$h^t = z \odot h^{t-1} + (1 - z) \odot h'$$

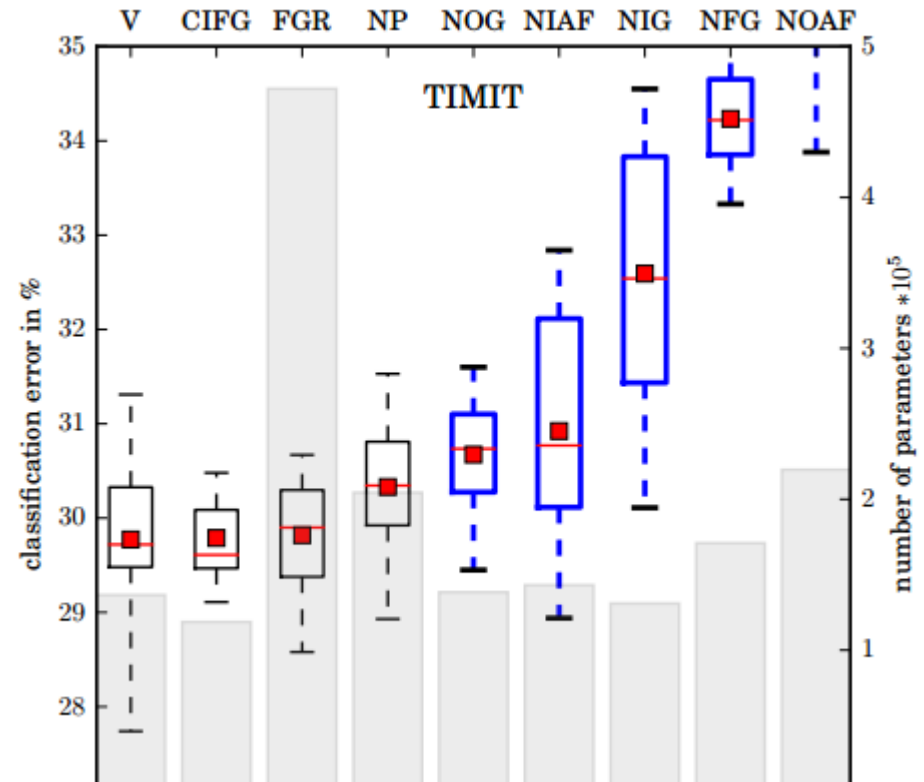


LSTM: A Search Space Odyssey



LSTM: A Search Space Odyssey

1. No Input Gate (NIG)
2. No Forget Gate (NFG)
3. No Output Gate (NOG)
4. No Input Activation Function (NIAF)
5. No Output Activation Function (NOAF)
6. No Peepholes (NP)
7. Coupled Input and Forget Gate (CIFG)
8. Full Gate Recurrence (FGR)



Standard LSTM works well

Simply LSTM: coupling input and forget gate, removing peephole

Forget gate is critical for performance

Output gate activation function is critical

An Empirical Exploration of Recurrent Network Architectures

Arch.	Arith.	XML	PTB
Tanh	0.29493	0.32050	0.08782
LSTM	0.89228	0.42470	0.08912
LSTM-f	0.29292	0.23356	0.08808
LSTM-i	0.75109	0.41371	0.08662
LSTM-o	0.86747	0.42117	0.08933
LSTM-b	0.90163	0.44434	0.08952
GRU	0.89565	0.45963	0.09069
MUT1	0.92135	0.47483	0.08968
MUT2	0.89735	0.47324	0.09036
MUT3	0.90728	0.46478	0.09161

LSTM-f/i/o: removing
forget/input/output gates

LSTM-b: large bias

Importance: forget > input > output

Large bias for forget gate is helpful

An Empirical Exploration of Recurrent Network Architectures

MUT1:

$$\begin{aligned}z &= \text{sigm}(W_{xz}x_t + b_z) \\r &= \text{sigm}(W_{xr}x_t + W_{hr}h_t + b_r) \\h_{t+1} &= \tanh(W_{hh}(r \odot h_t) + \tanh(x_t) + b_h) \odot z \\&+ h_t \odot (1 - z)\end{aligned}$$

MUT2:

$$\begin{aligned}z &= \text{sigm}(W_{xz}x_t + W_{hz}h_t + b_z) \\r &= \text{sigm}(x_t + W_{hr}h_t + b_r) \\h_{t+1} &= \tanh(W_{hh}(r \odot h_t) + W_{xh}x_t + b_h) \odot z \\&+ h_t \odot (1 - z)\end{aligned}$$

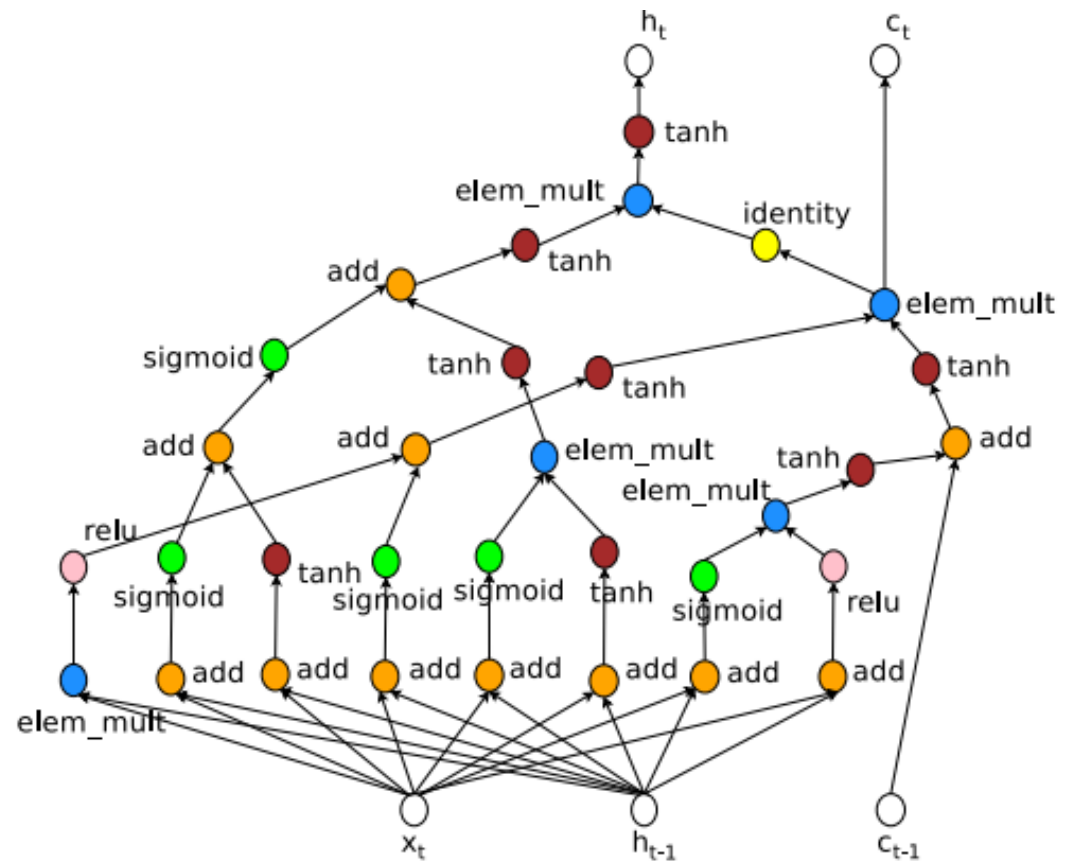
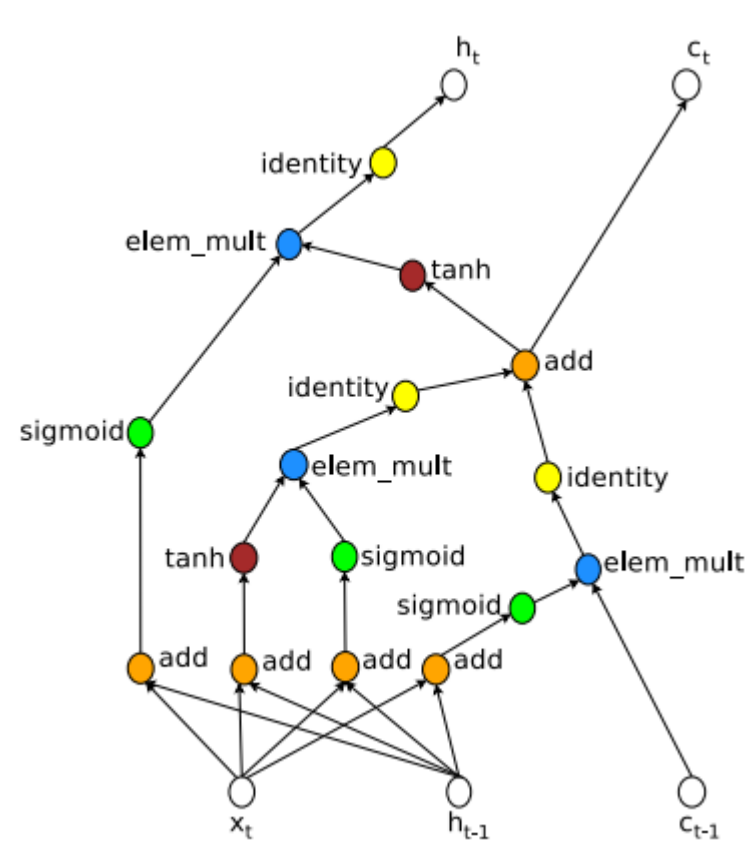
MUT3:

$$\begin{aligned}z &= \text{sigm}(W_{xz}x_t + W_{hz} \tanh(h_t) + b_z) \\r &= \text{sigm}(W_{xr}x_t + W_{hr}h_t + b_r) \\h_{t+1} &= \tanh(W_{hh}(r \odot h_t) + W_{xh}x_t + b_h) \odot z \\&+ h_t \odot (1 - z)\end{aligned}$$

Neural Architecture Search with Reinforcement Learning

LSTM

From Reinforcement Learning

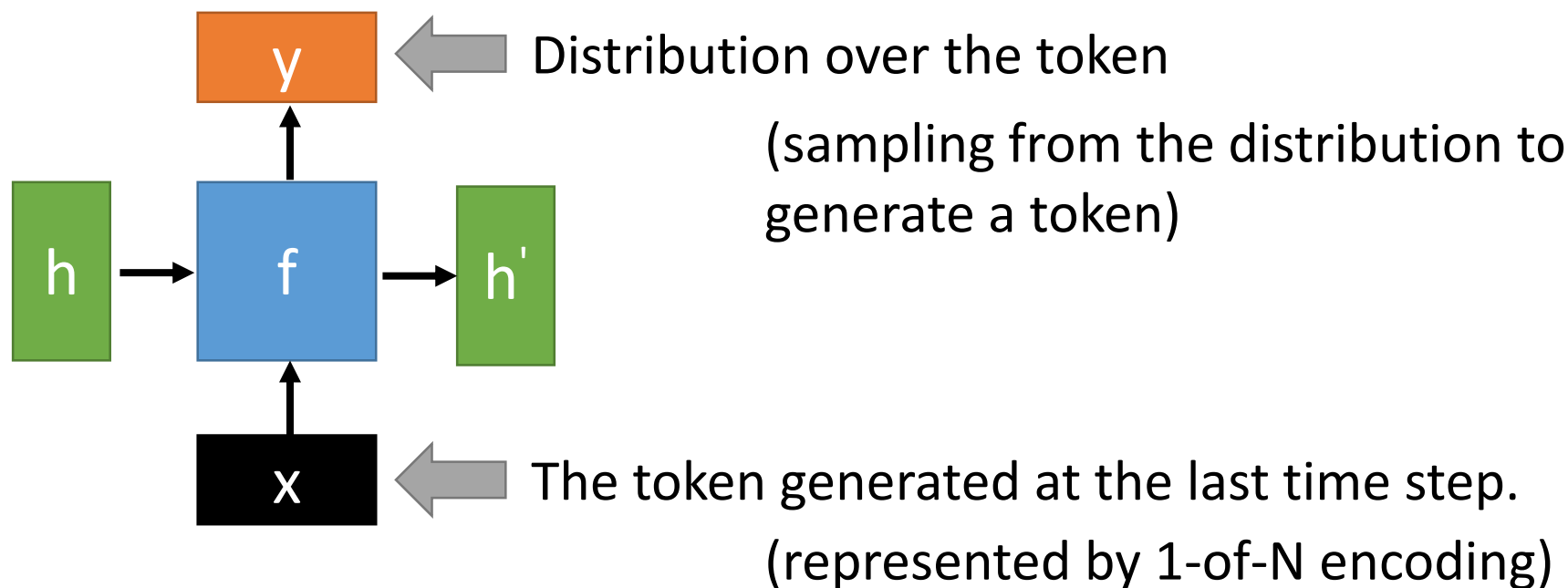


Sequence Generation

Generation



- Sentences are composed of characters/words
- Generating a character/word at each time by RNN



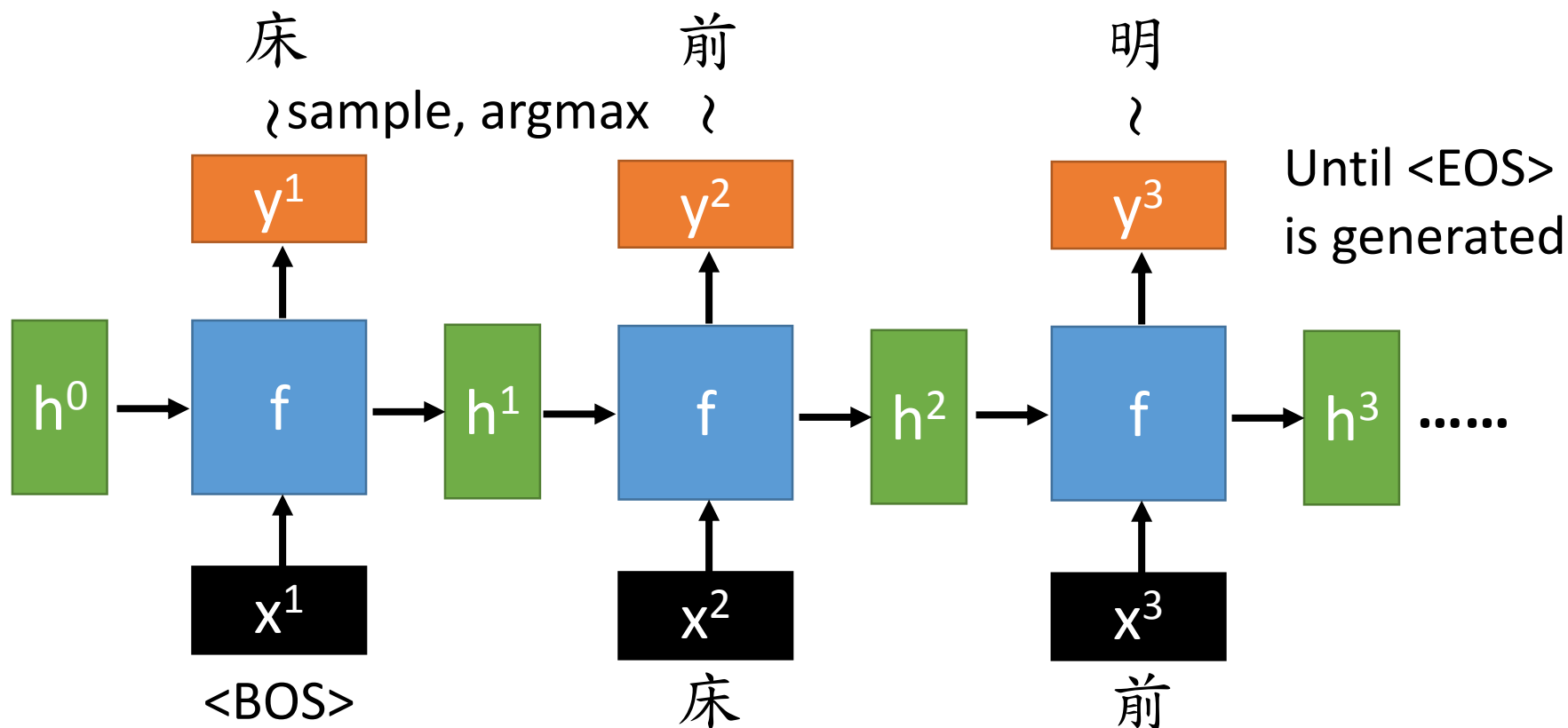
Generation

$$y^1: P(w | \langle \text{BOS} \rangle)$$

$$y^2: P(w | \langle \text{BOS} \rangle, \text{床})$$

$$y^3: P(w | \langle \text{BOS} \rangle, \text{床}, \text{前})$$

- Sentences are composed of characters/words
- Generating a character/word at each time by RNN

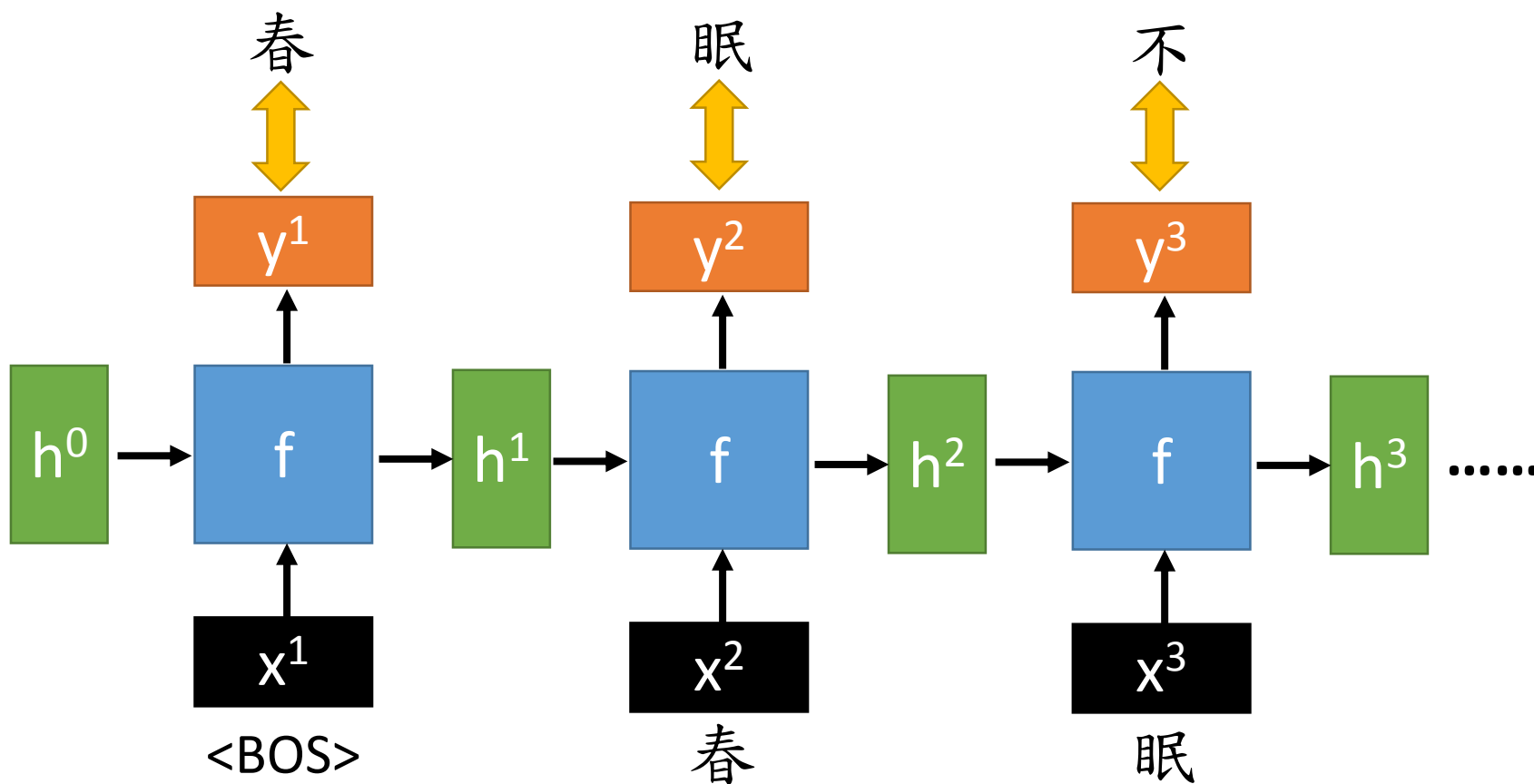


Generation

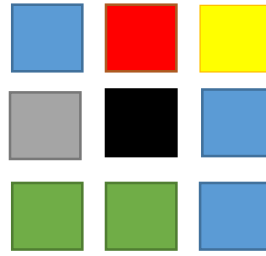
↕ : minimizing cross-entropy

- Training

Training data: 春 眠 不 覺 曉



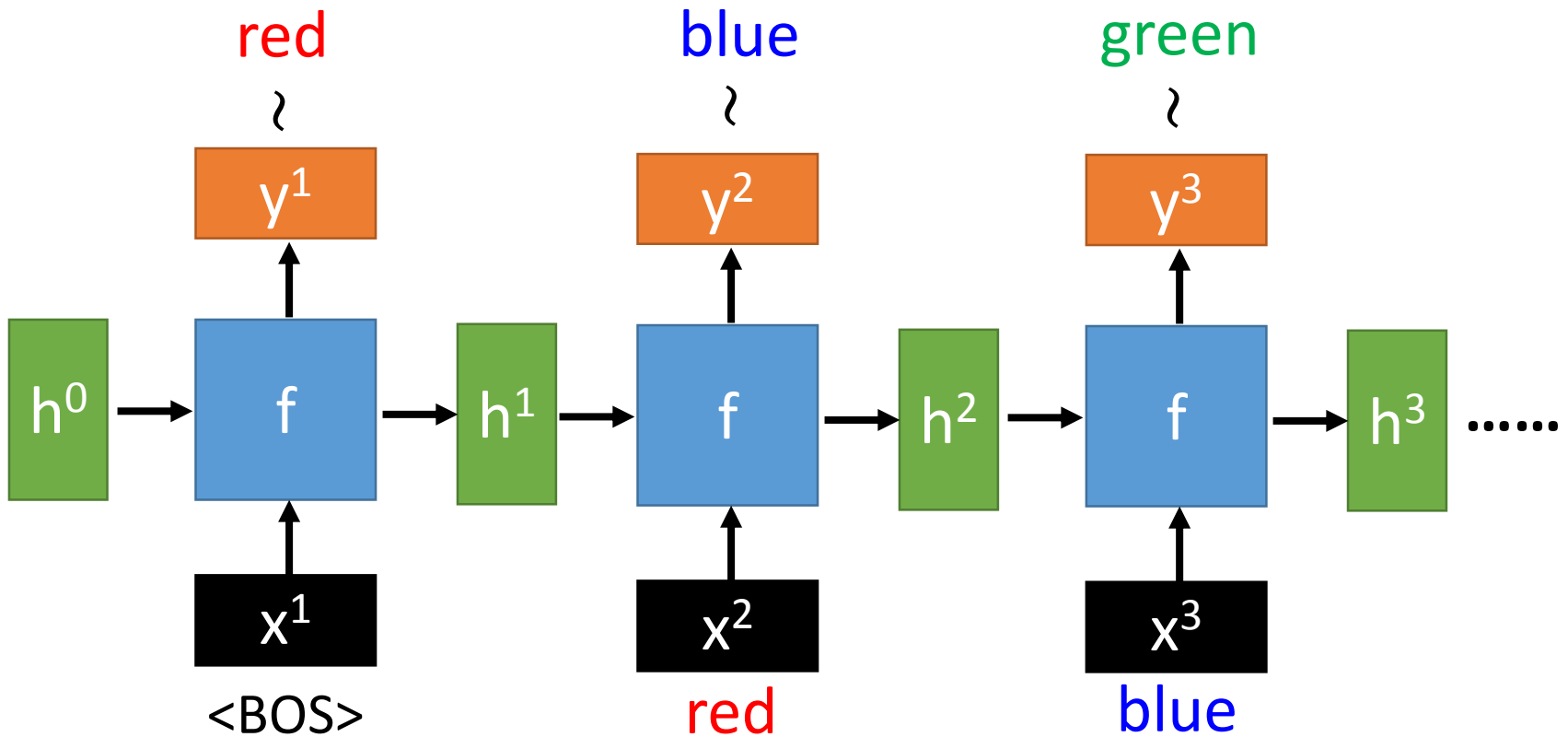
Generation



Consider as a sentence
blue red yellow gray

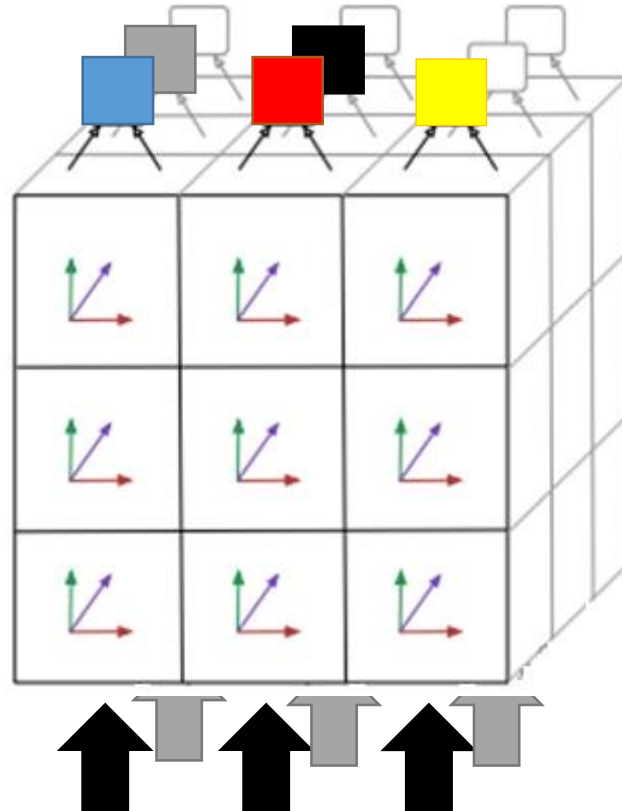
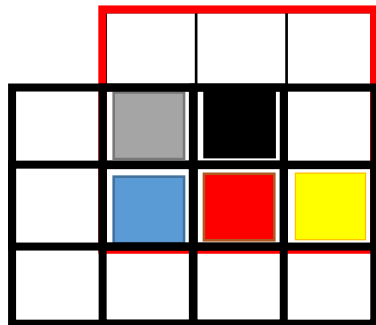
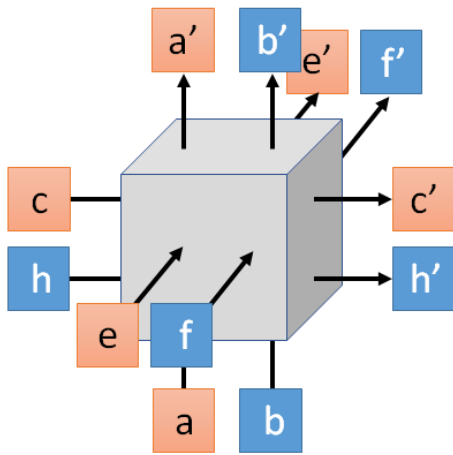
Train a RNN based on the
“sentences”

- Images are composed of pixels
- Generating a pixel at each time by RNN

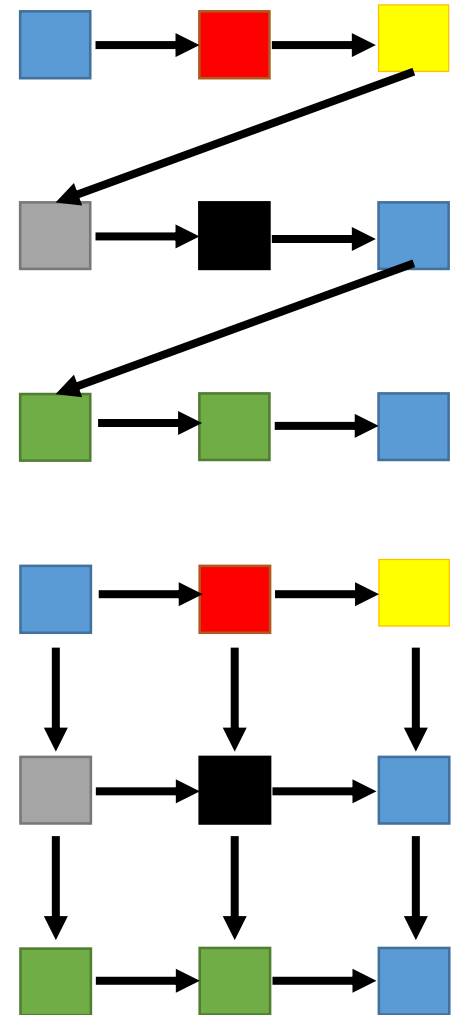


Generation - PixelRNN

- Images are composed of pixels



3 x 3 images



Conditional Sequence Generation

Conditional Generation

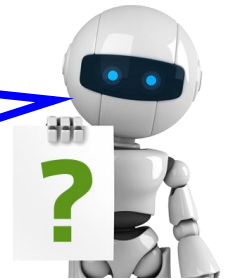
- We don't want to simply generate some random sentences.
- Generate sentences based on conditions:

Caption Generation

Given
condition:

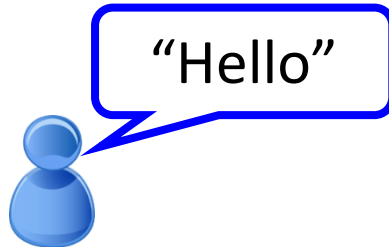


“A young girl
is dancing.”

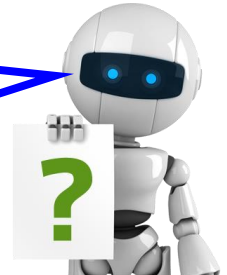


Chat-bot

Given
condition:



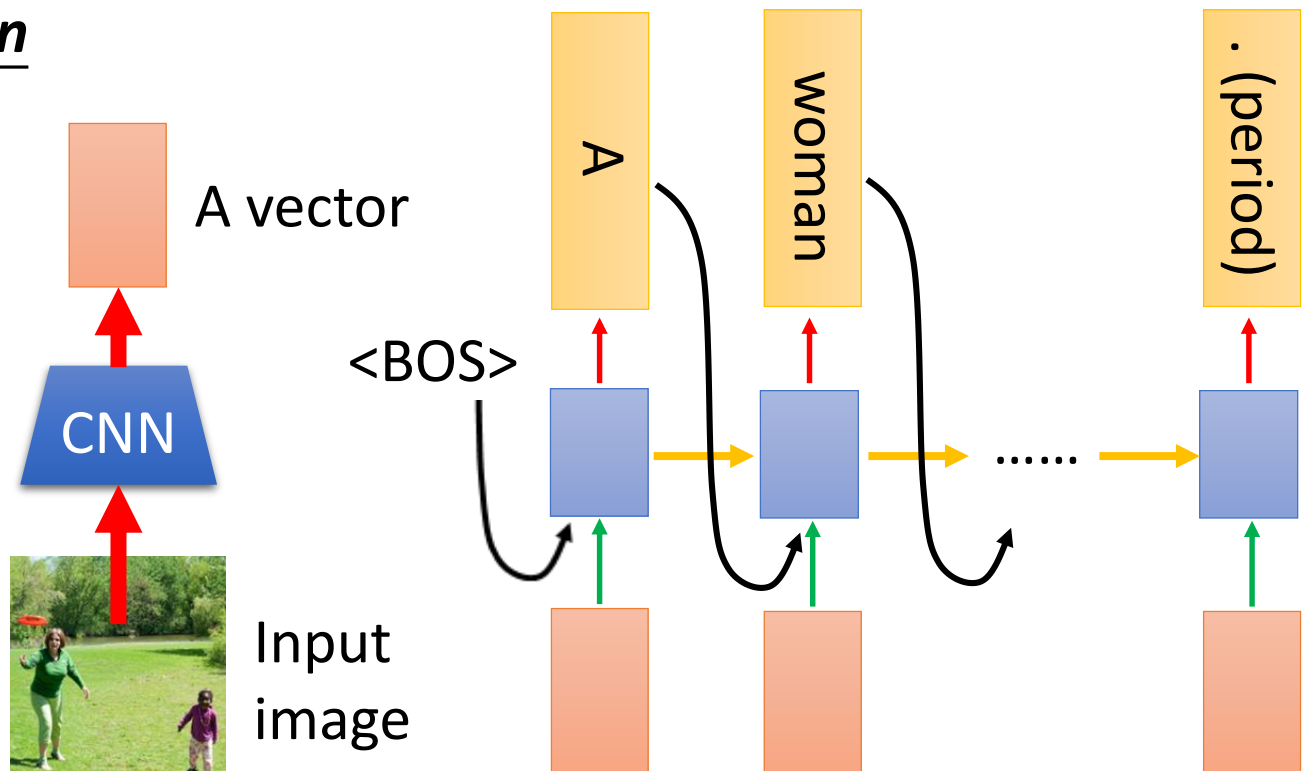
“Hello. Nice
to see you.”



Conditional Generation

- Represent the input condition as a vector, and consider the vector as the input of RNN generator

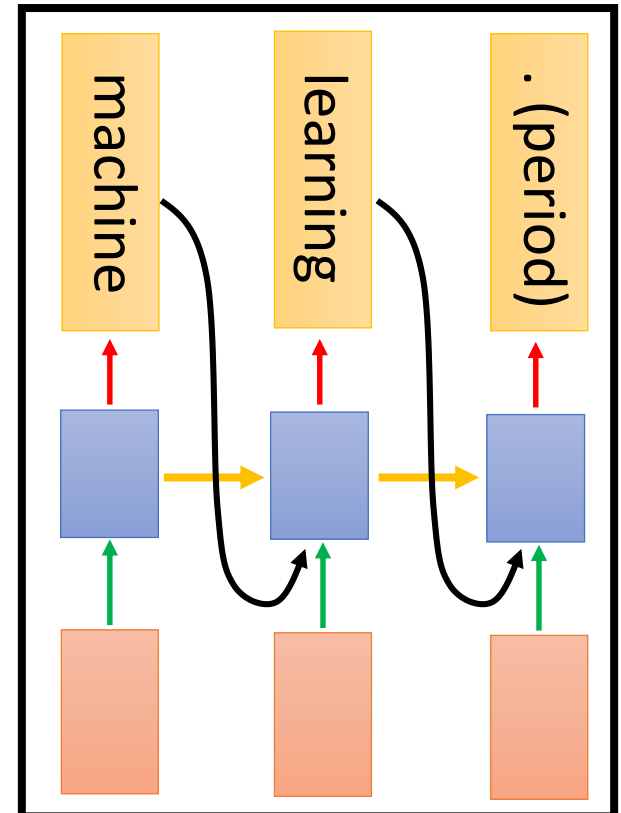
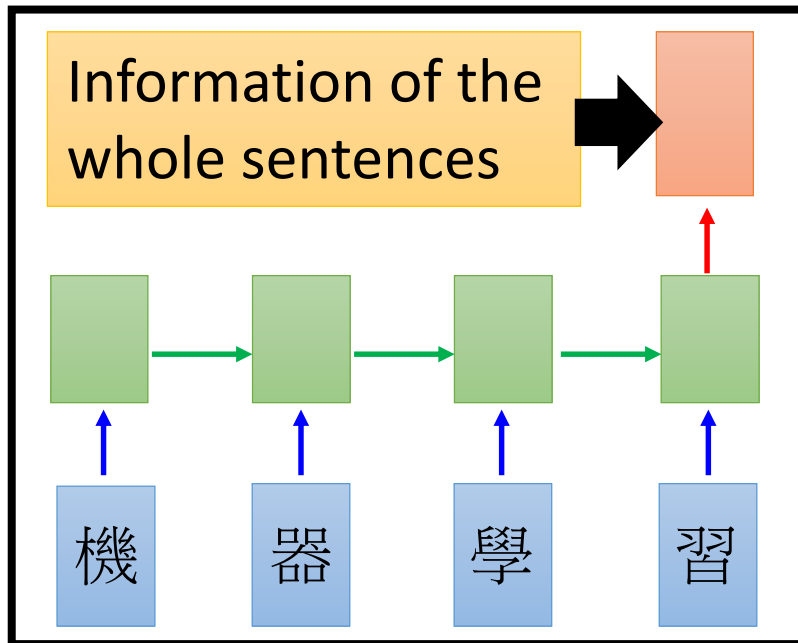
Image Caption Generation



Conditional Generation

Sequence-to-sequence learning

- Represent the input condition as a vector, and consider the vector as the input of RNN generator
- E.g. Machine translation / Chat-bot



Encoder ← Jointly train → Decoder

Conditional Generation

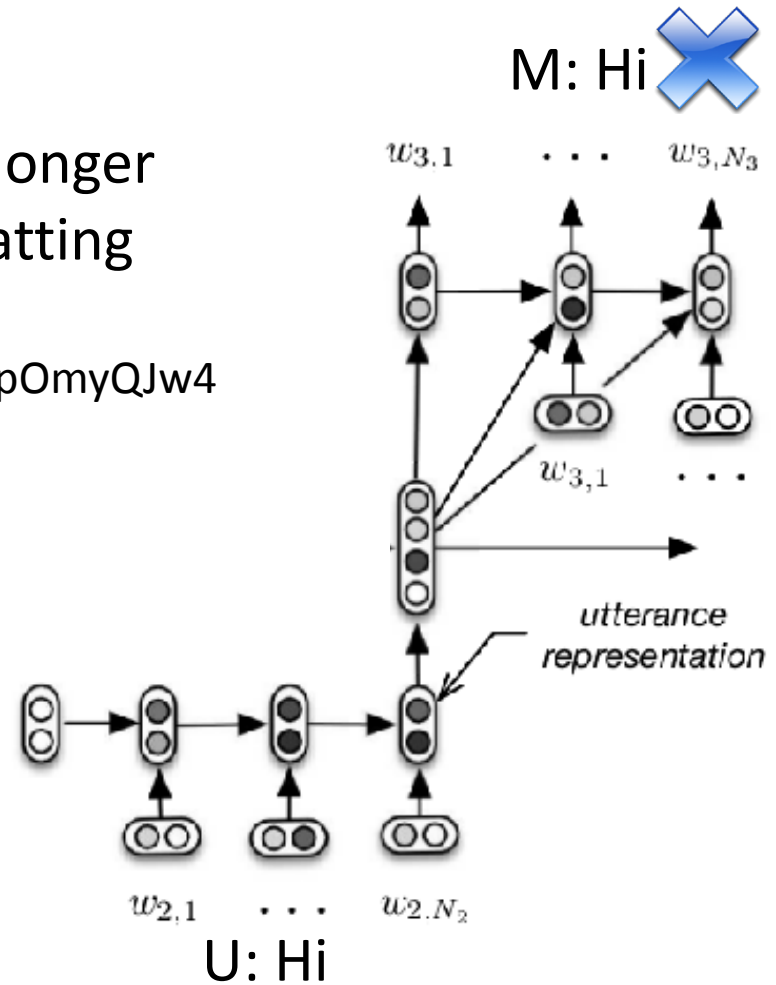
M: Hello

U: Hi

M: Hi

<https://www.youtube.com/watch?v=e2MpOmyQJw4>

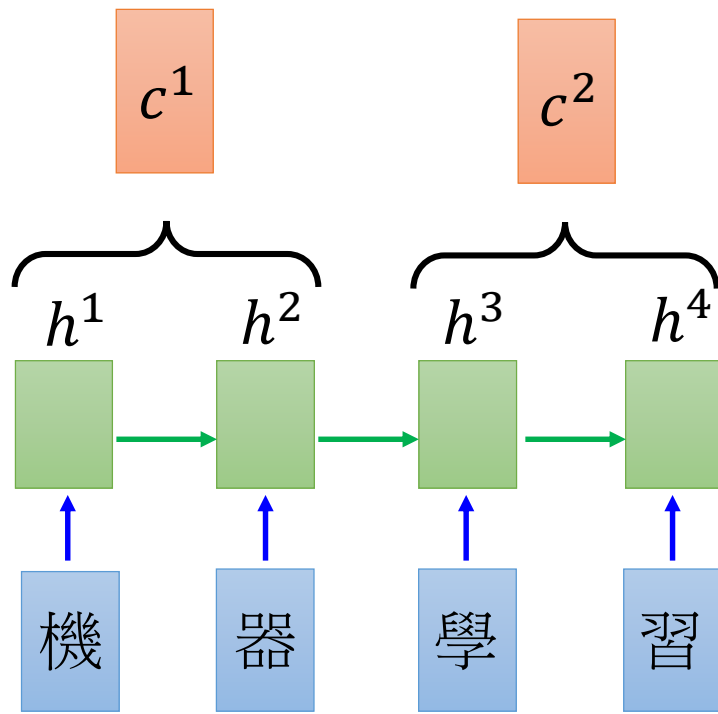
Need to consider longer context during chatting



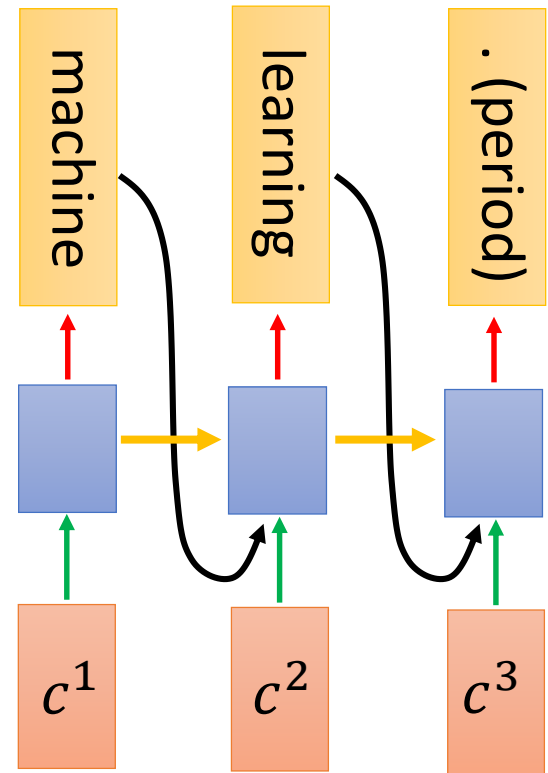
M: Hello

U: Hi

Dynamic Conditional Generation



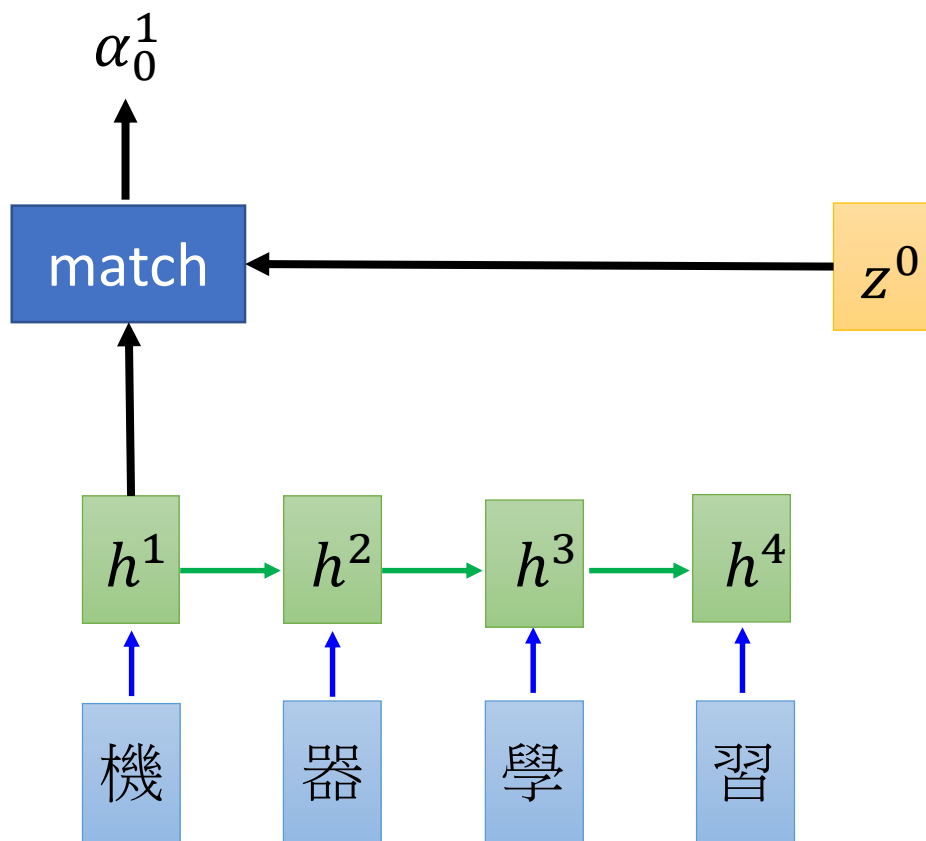
Encoder



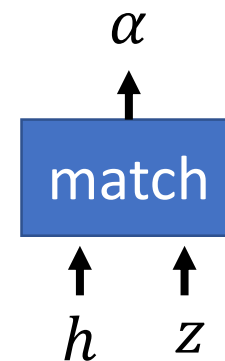
Decoder

Machine Translation

- Attention-based model



Jointly learned
with other part
of the network



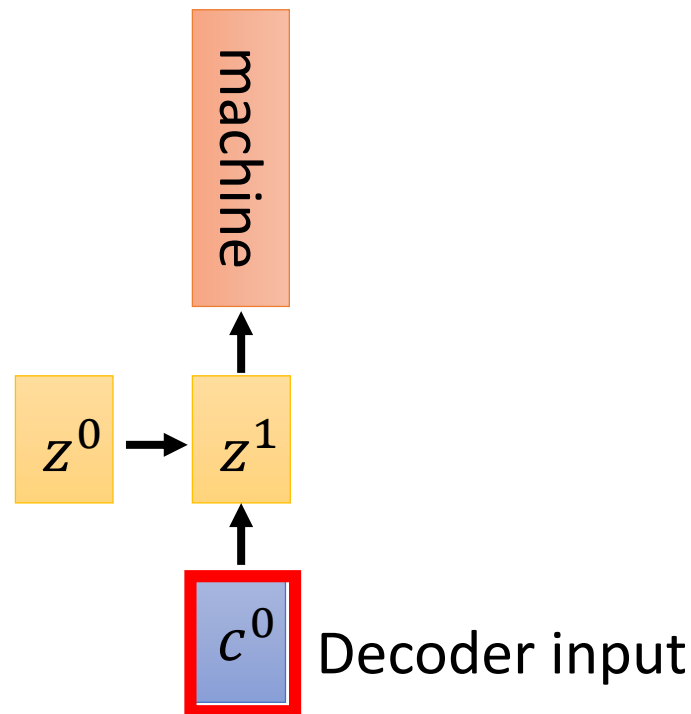
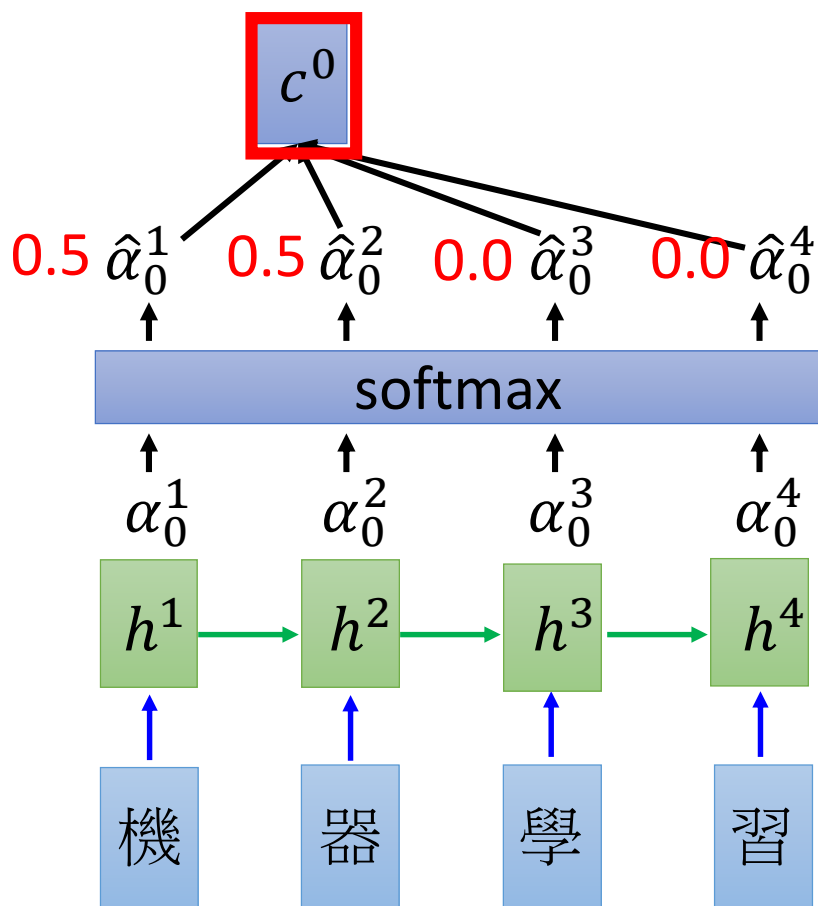
What is **match** ?

Design by yourself

- Cosine similarity of z and h
- Small NN whose input is z and h , output a scalar
- $\alpha = h^T W z$

Machine Translation

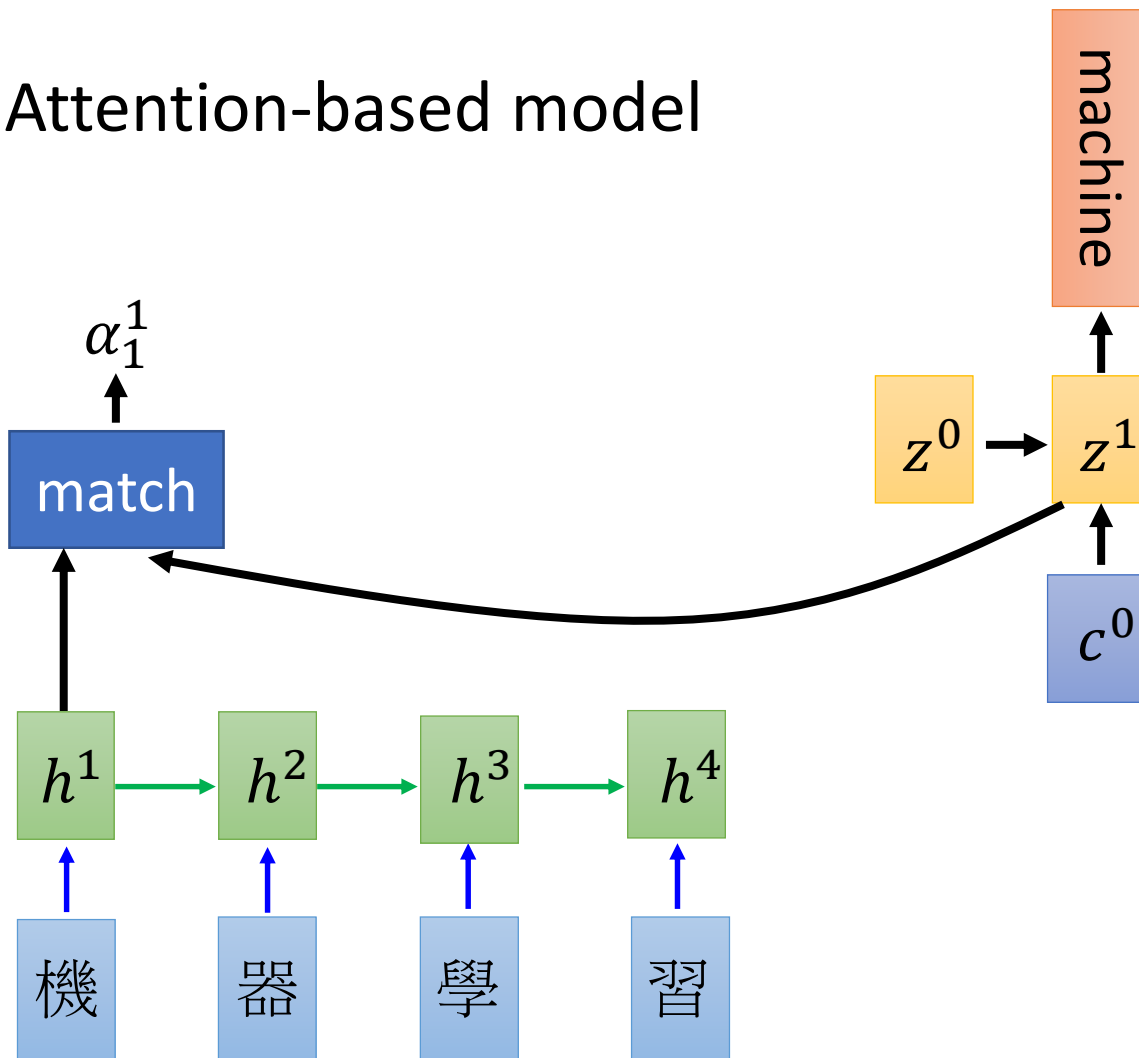
- Attention-based model



$$c^0 = \sum \hat{\alpha}_0^i h^i$$
$$= 0.5h^1 + 0.5h^2$$

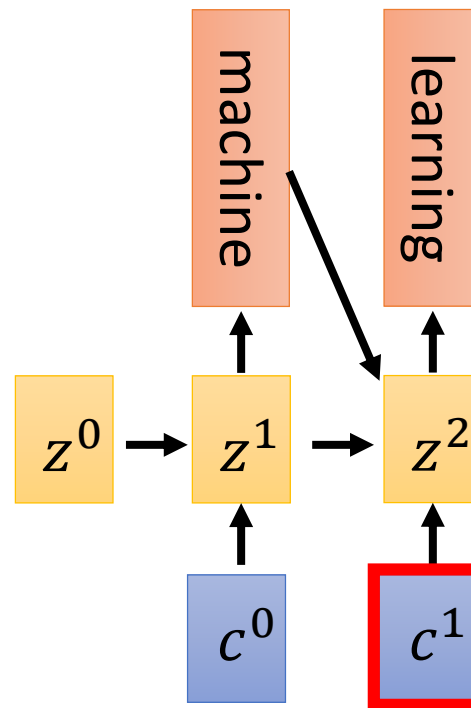
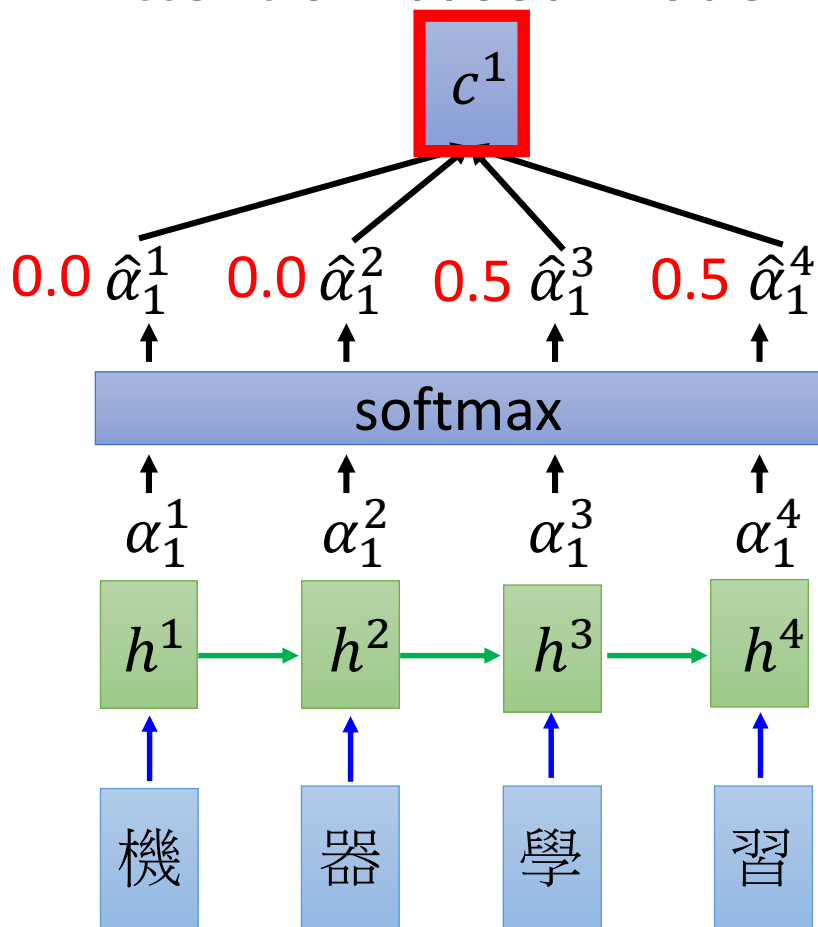
Machine Translation

- Attention-based model



Machine Translation

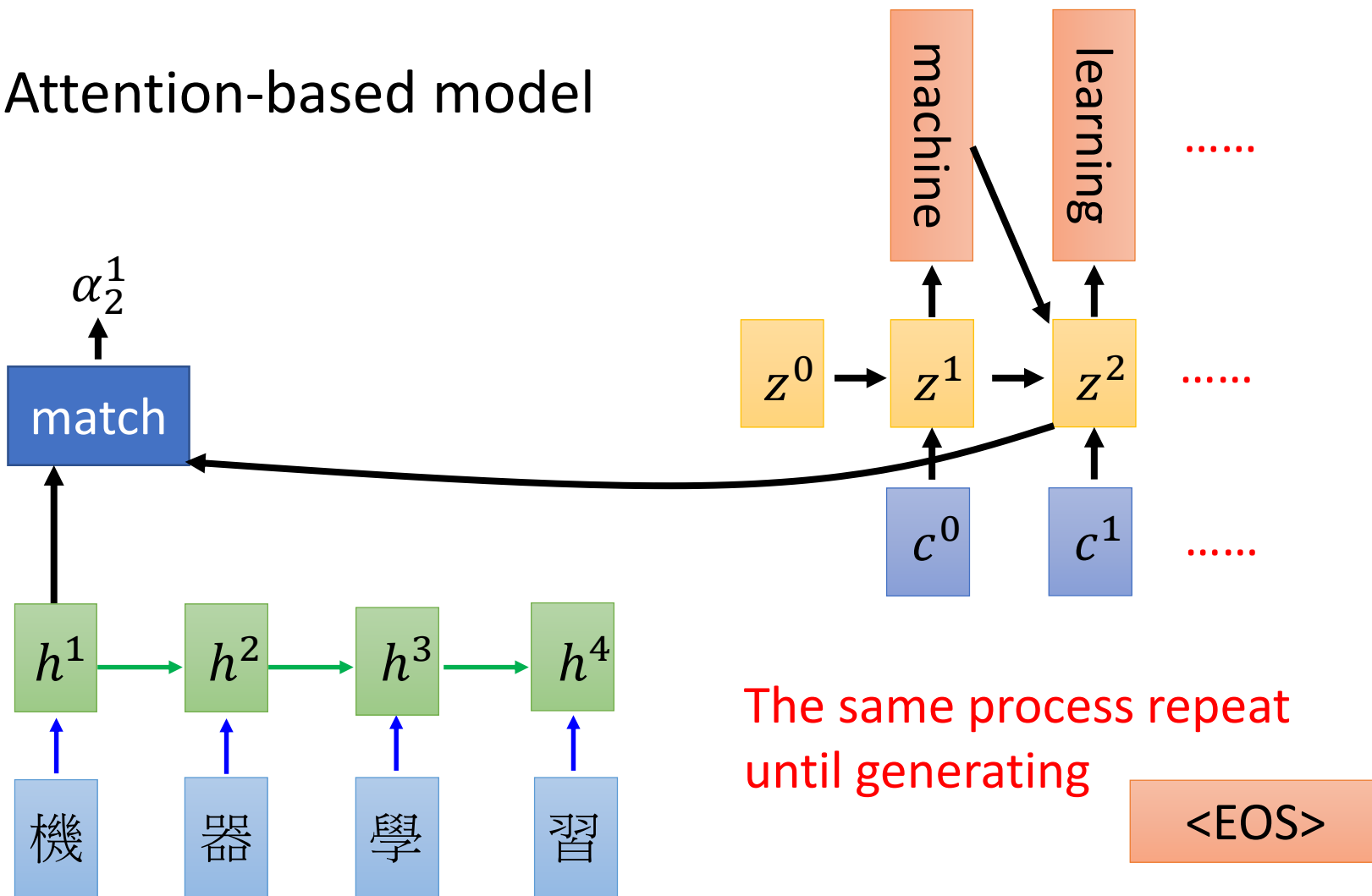
- Attention-based model



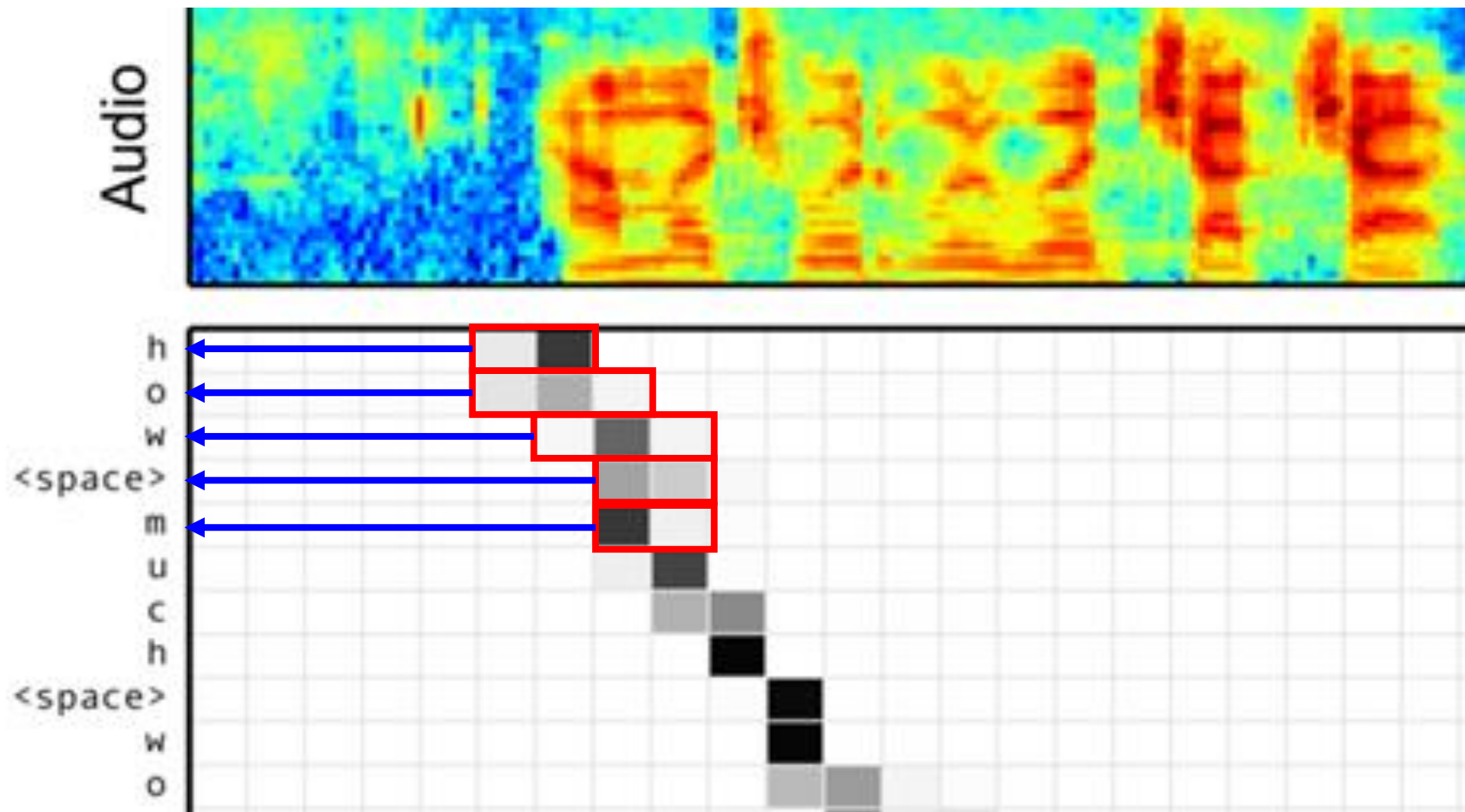
$$c^1 = \sum \hat{\alpha}_1^i h^i$$
$$= 0.5h^3 + 0.5h^4$$

Machine Translation

- Attention-based model



Speech Recognition



Model	Clean WER	Noisy WER
CLDNN-HMM [22]	8.0	8.9
LAS	14.1	16.5
LAS + LM Rescoring	10.3	12.0

William Chan, Navdeep Jaitly, Quoc V. Le, Oriol Vinyals, "Listen, Attend and Spell", ICASSP, 2016

Image Caption Generation

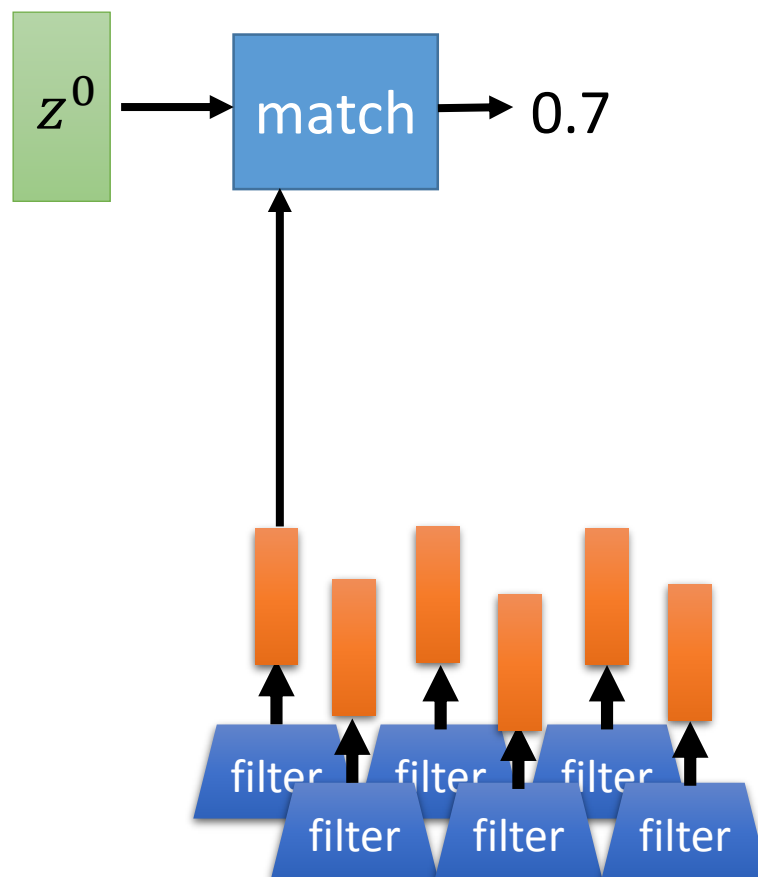
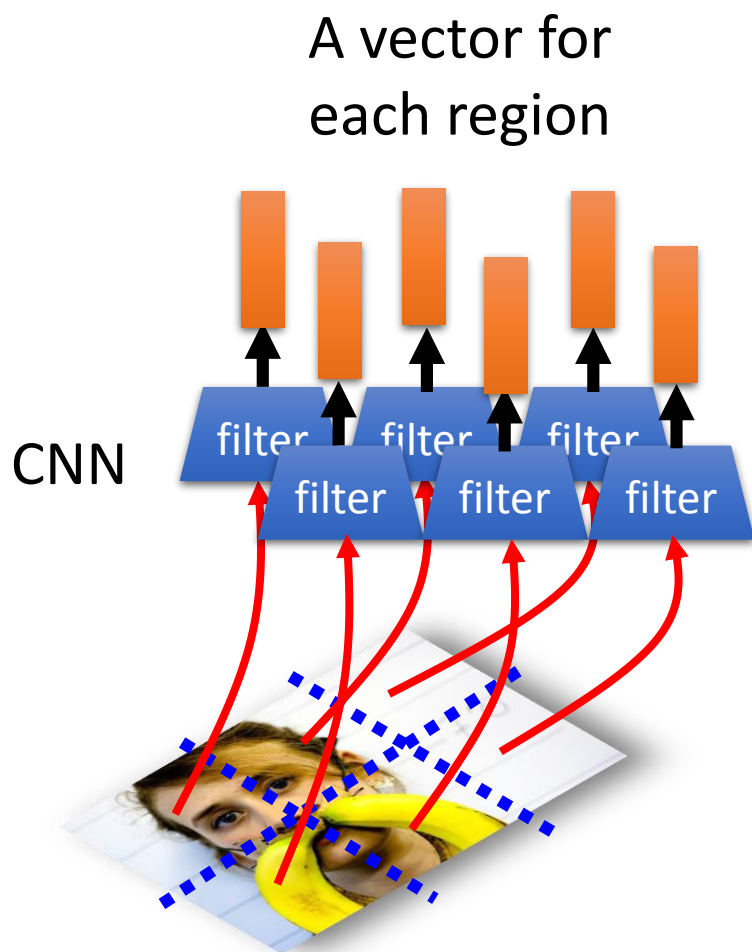


Image Caption Generation

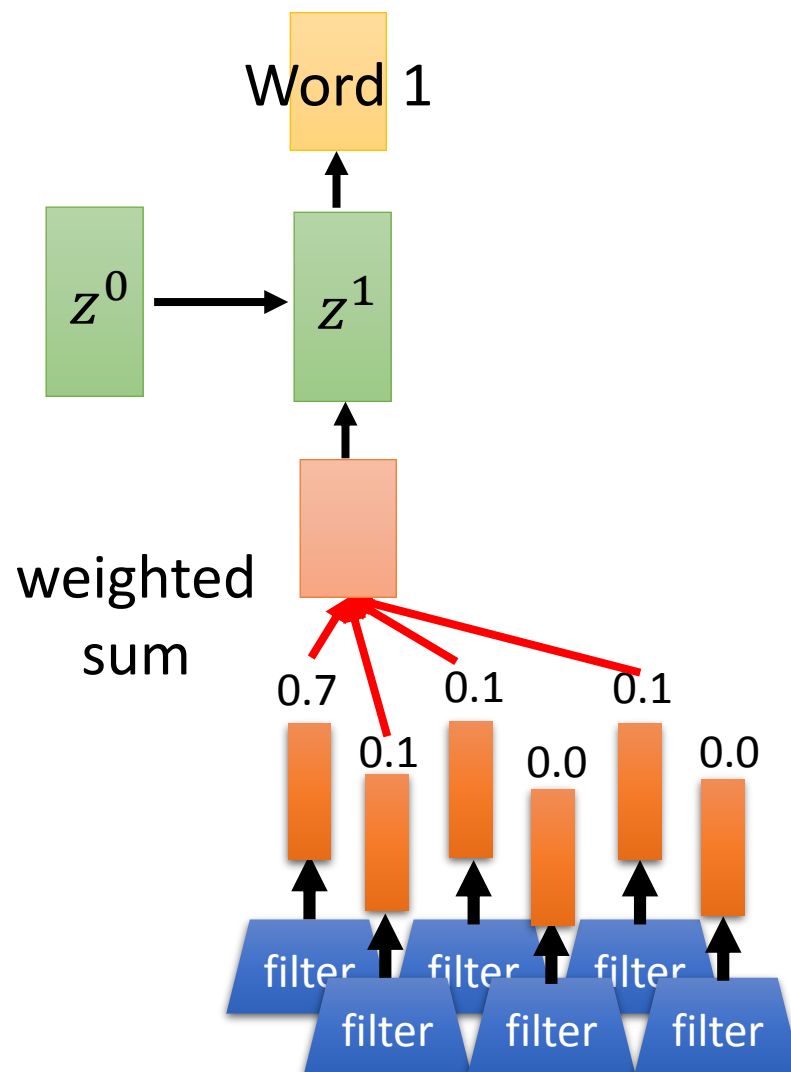
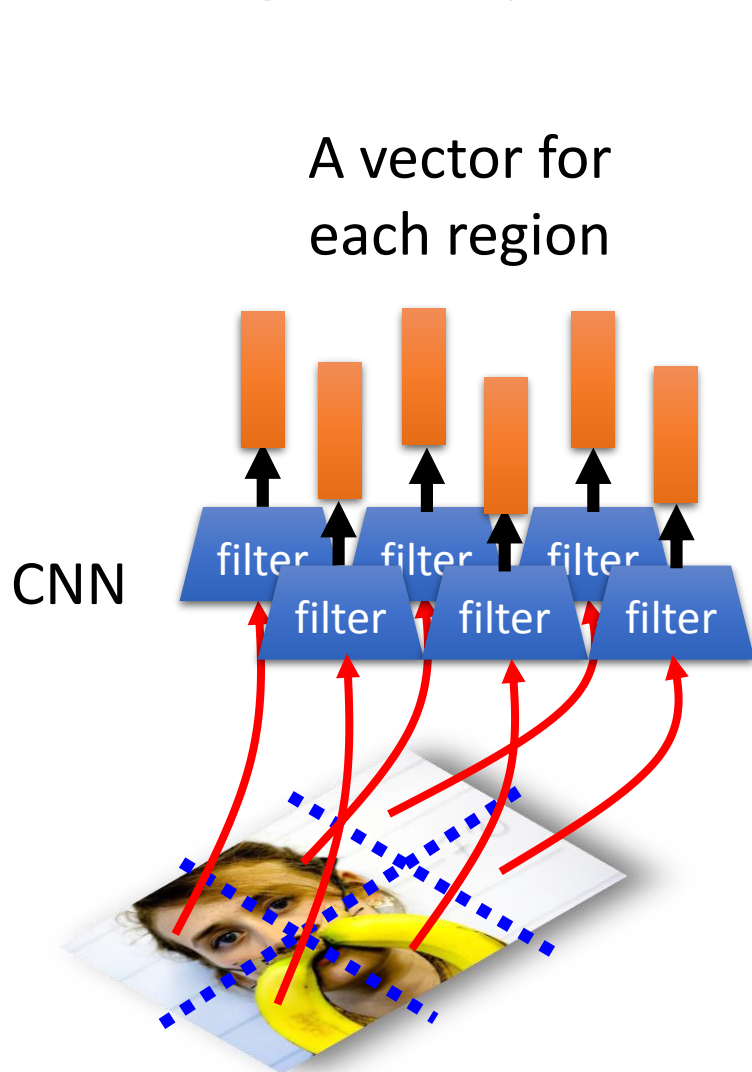


Image Caption Generation

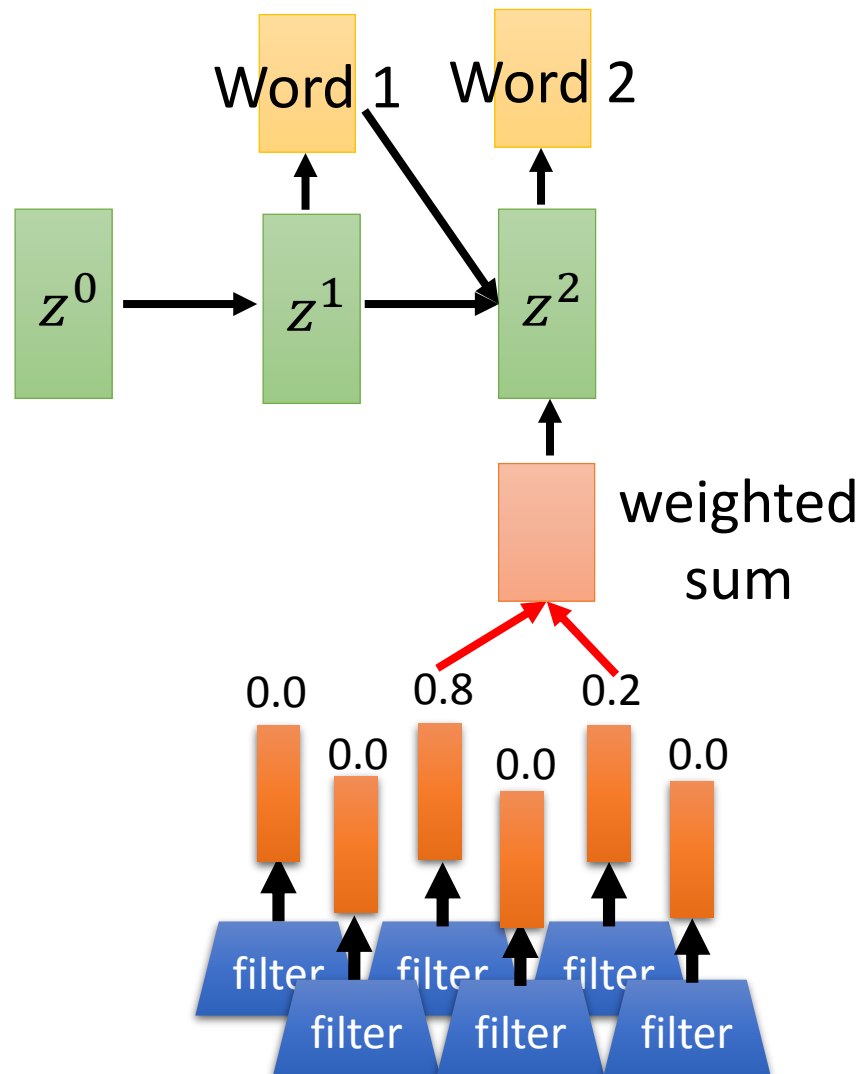
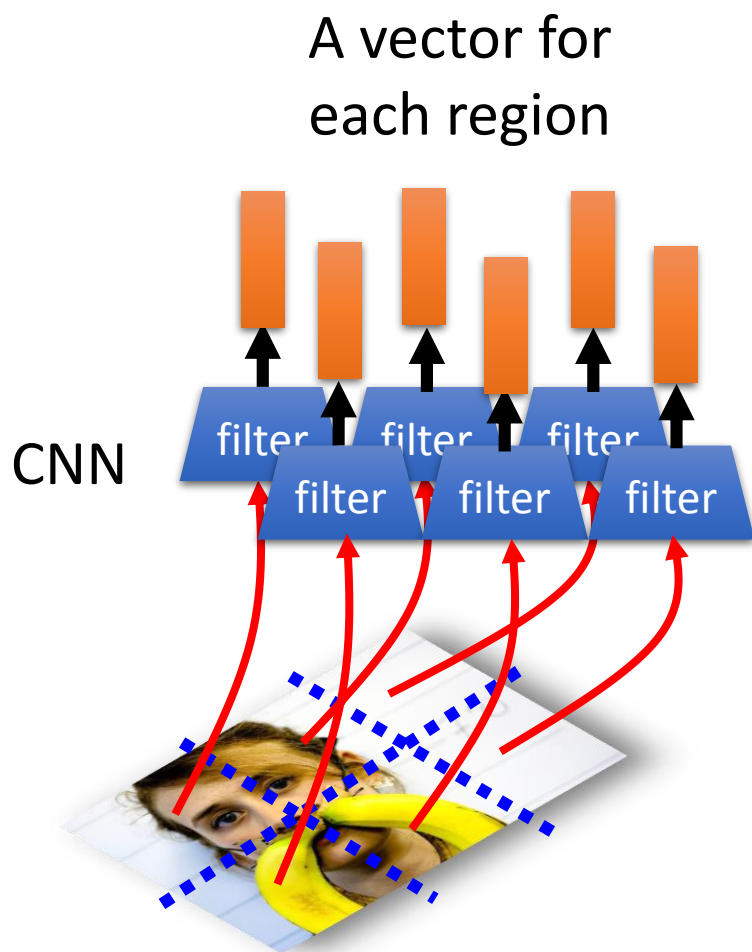
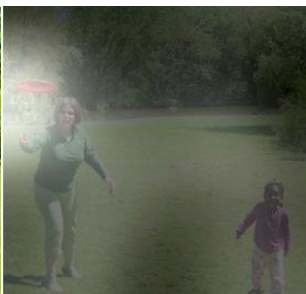


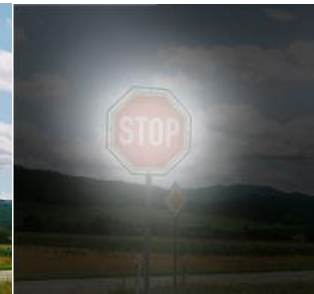
Image Caption Generation



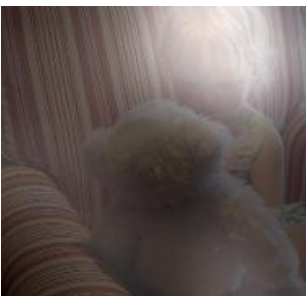
A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



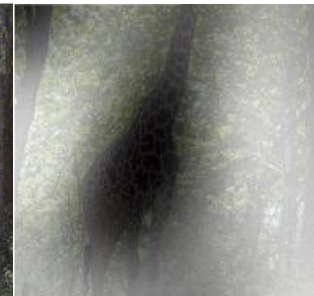
A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



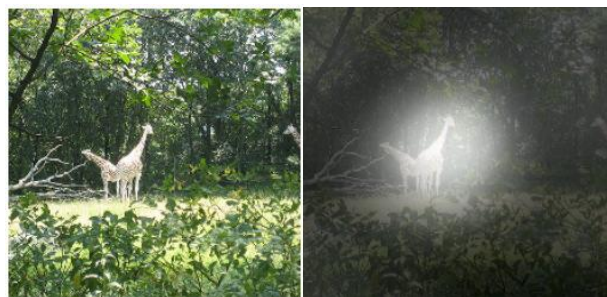
A group of people sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

Kelvin Xu, Jimmy Ba, Ryan Kiros, Kyunghyun Cho, Aaron Courville, Ruslan Salakhutdinov, Richard Zemel, Yoshua Bengio, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML, 2015

Image Caption Generation



A large white bird standing in a forest.



A woman holding a clock in her hand.



A man wearing a hat and a hat on a skateboard.



A person is standing on a beach with a surfboard.



A woman is sitting at a table with a large pizza.



A man is talking on his cell phone while another man watches.

Kelvin Xu, Jimmy Ba, Ryan Kiros, Kyunghyun Cho, Aaron Courville, Ruslan Salakhutdinov, Richard Zemel, Yoshua Bengio, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML, 2015



Ref: A man and a woman ride a motorcycle

A **man** and a **woman** are **talking** on the **road**



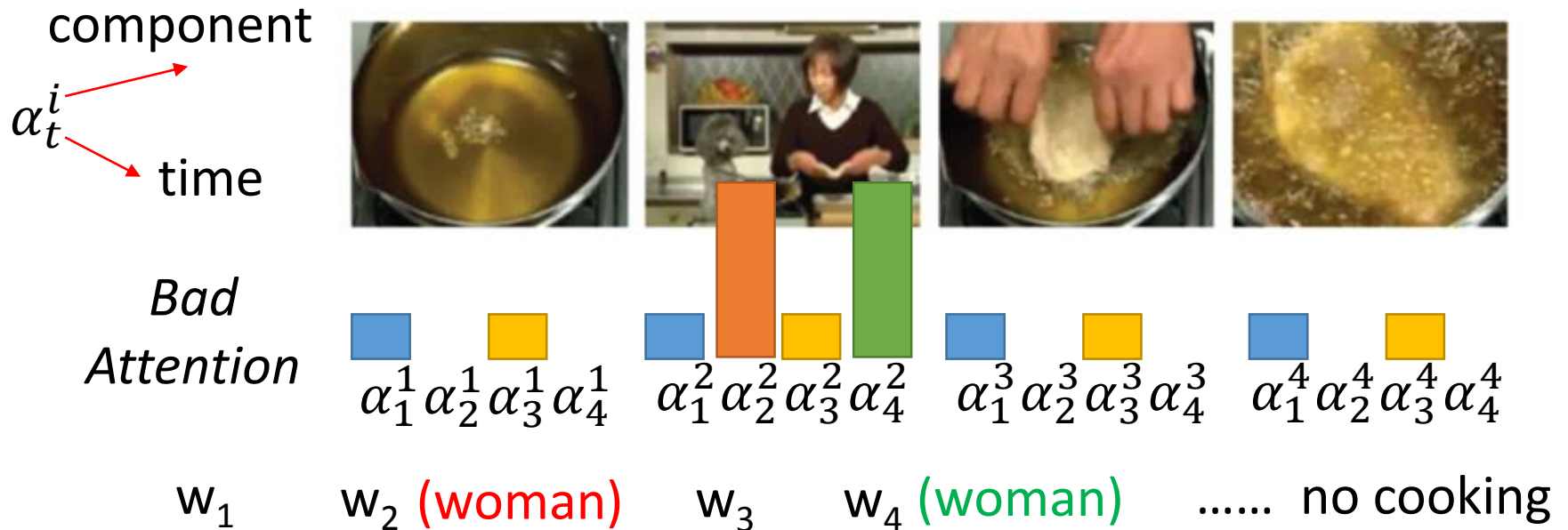
Ref: A woman is frying food

Someone is **frying** a **fish** in a **pot**

Tips for Generation

Kelvin Xu, Jimmy Ba, Ryan Kiros, Kyunghyun Cho, Aaron Courville, Ruslan Salakhutdinov, Richard Zemel, Yoshua Bengio, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML, 2015

Attention



Good Attention: each input component has approximately the same attention weight

E.g. Regularization term: $\sum_i \left(\tau - \sum_t \alpha_t^i \right)^2$

For each component

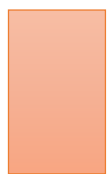
Over the generation

Mismatch between Train and Test

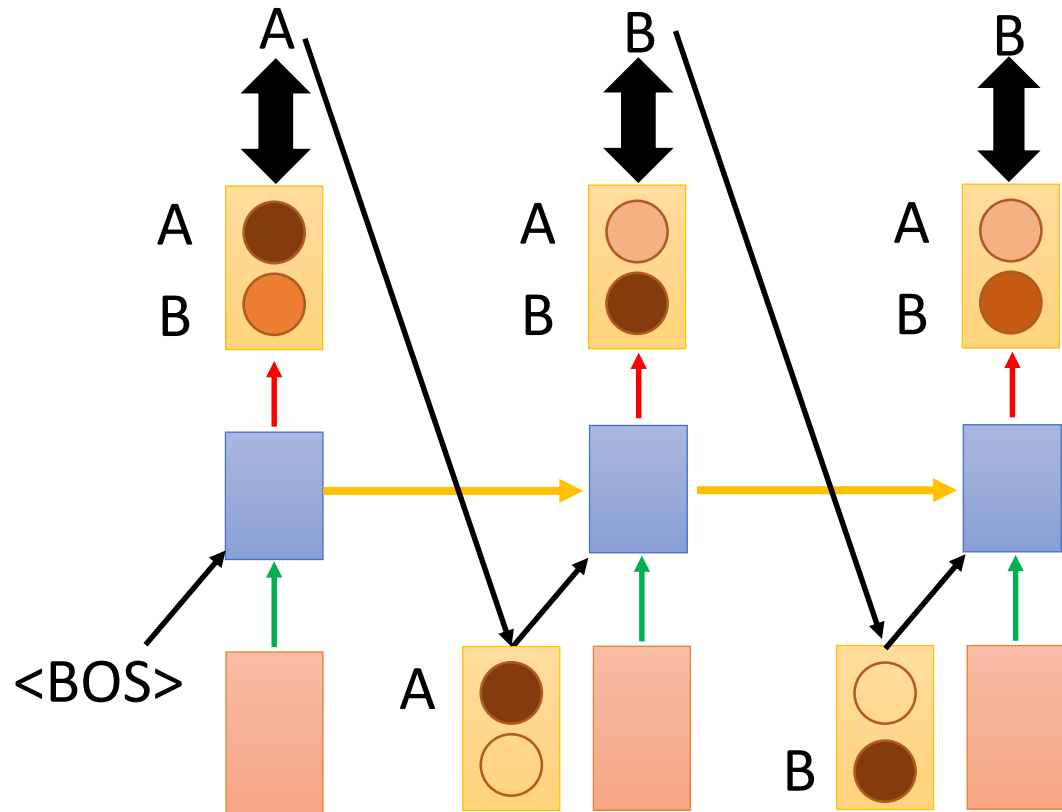
- Training

$$C = \sum_t C_t$$

Minimizing cross-entropy of each component

 : condition

Reference:



Mismatch between Train and Test

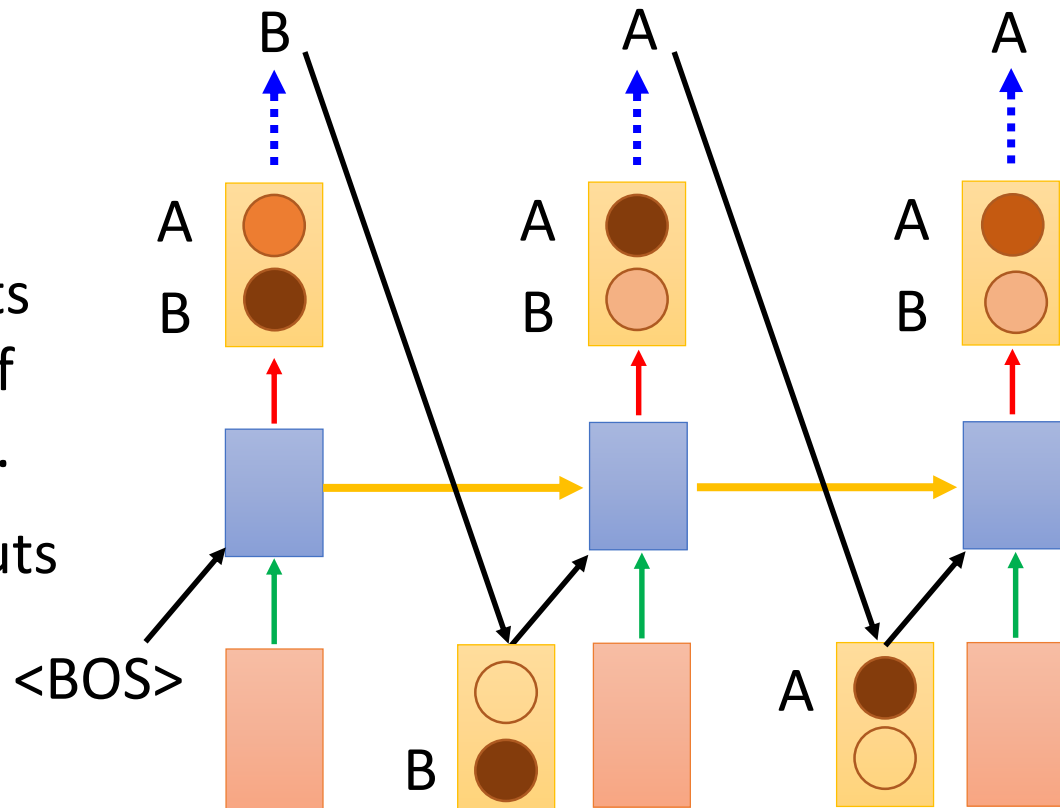
- Generation

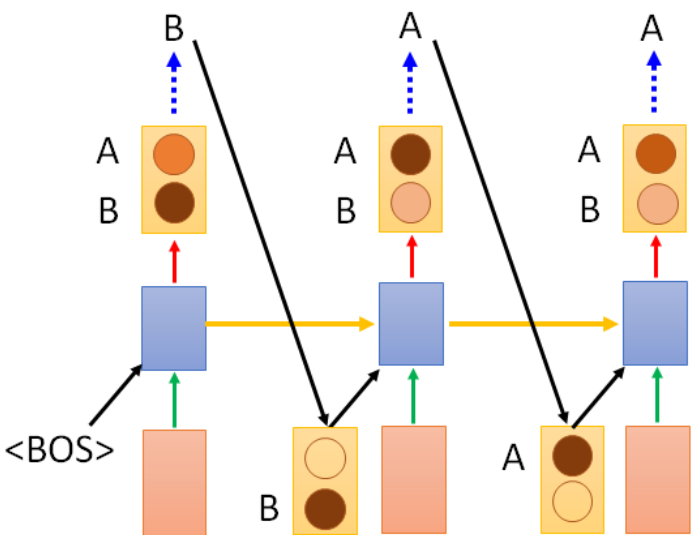
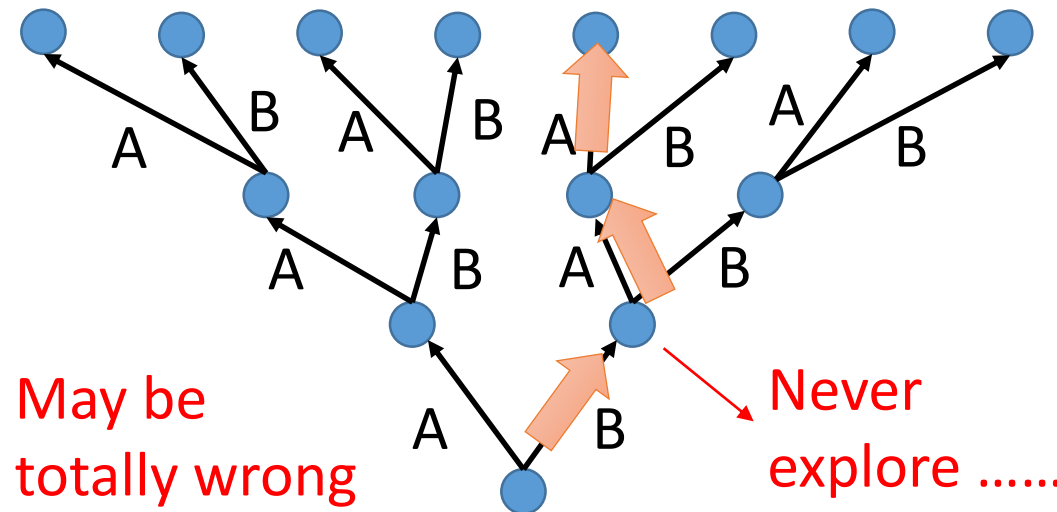
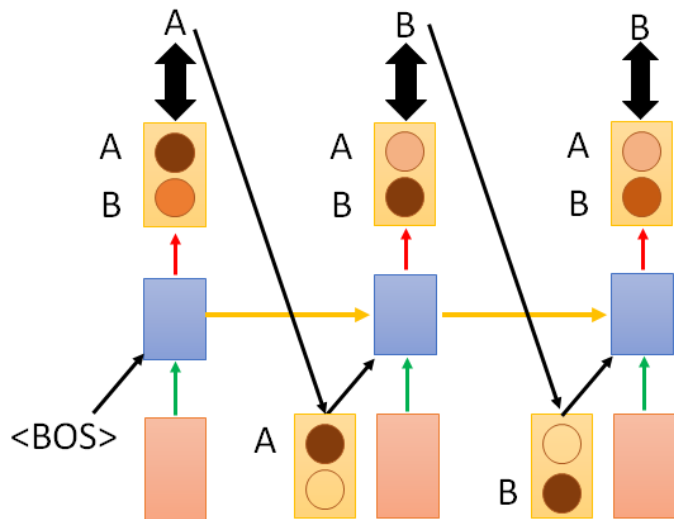
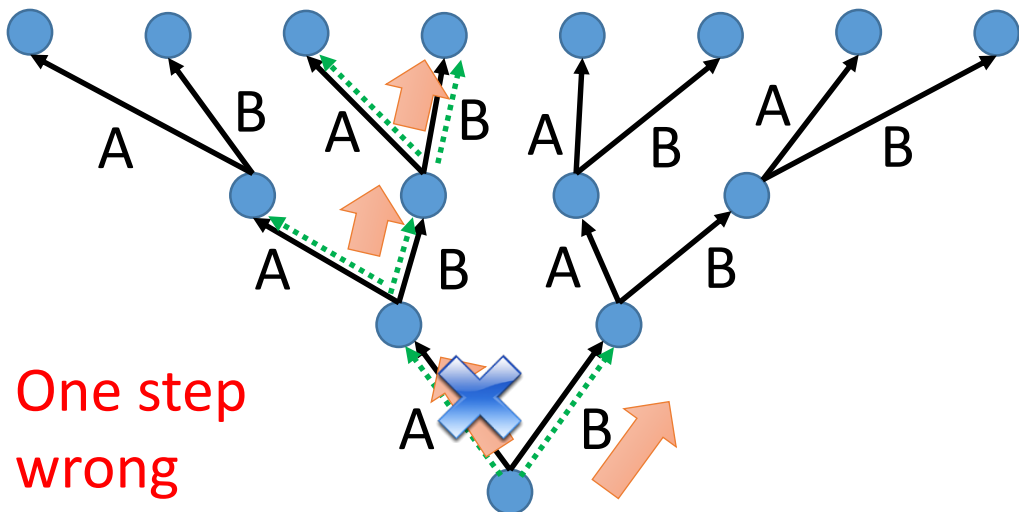
We do not know the reference

Testing: The inputs are the outputs of the last time step.

Training: The inputs are reference.

Exposure Bias





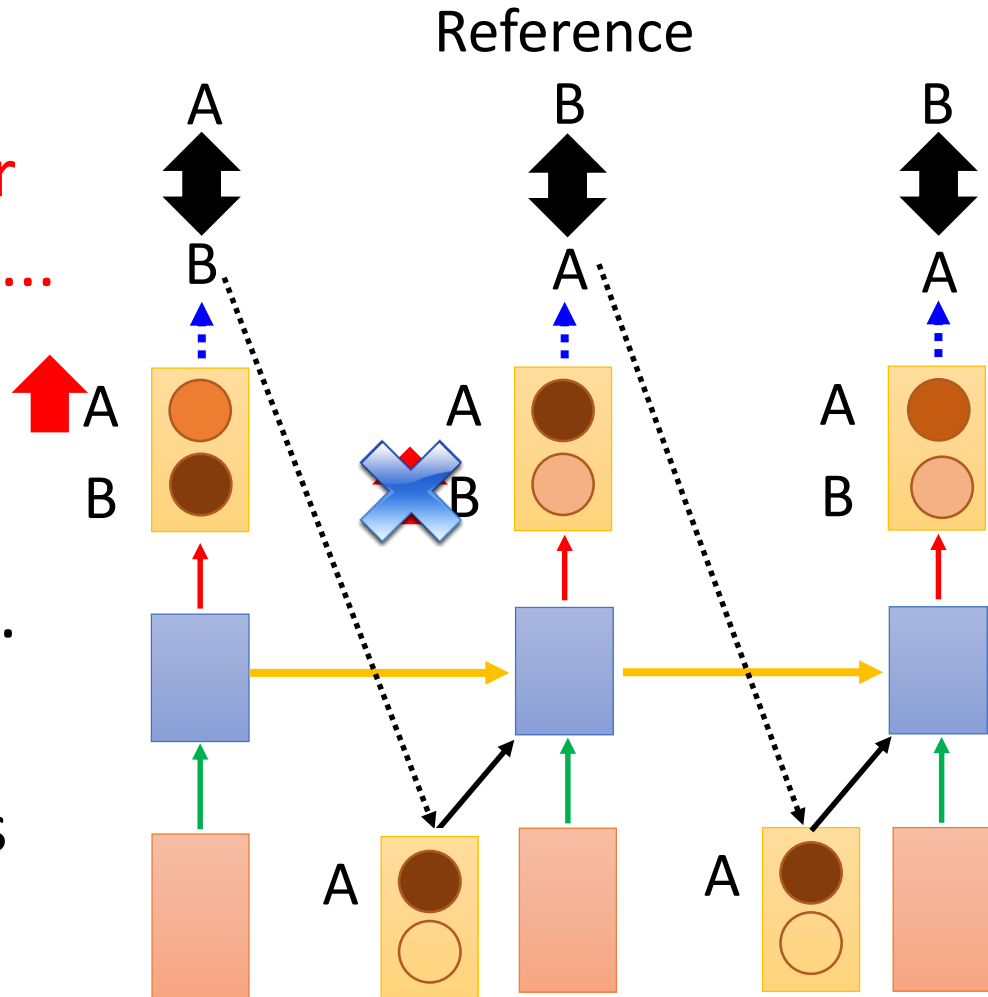
一步錯，步步錯

Modifying Training Process?

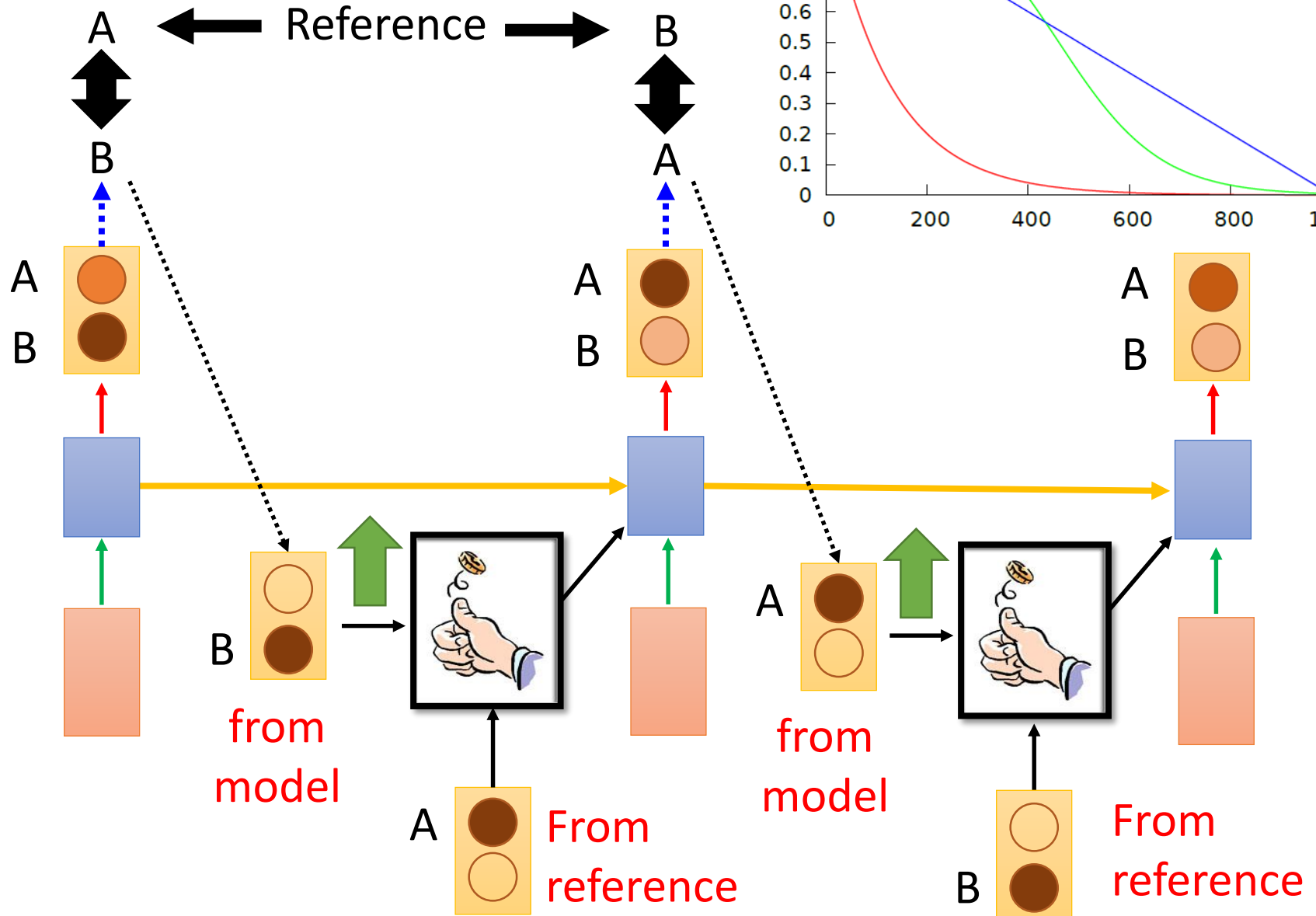
When we try to decrease the loss for both steps 1 and 2

Training is matched to testing.

In practice, it is hard to train in this way.



Scheduled Sampling



Scheduled Sampling

- Caption generation on MSCOCO

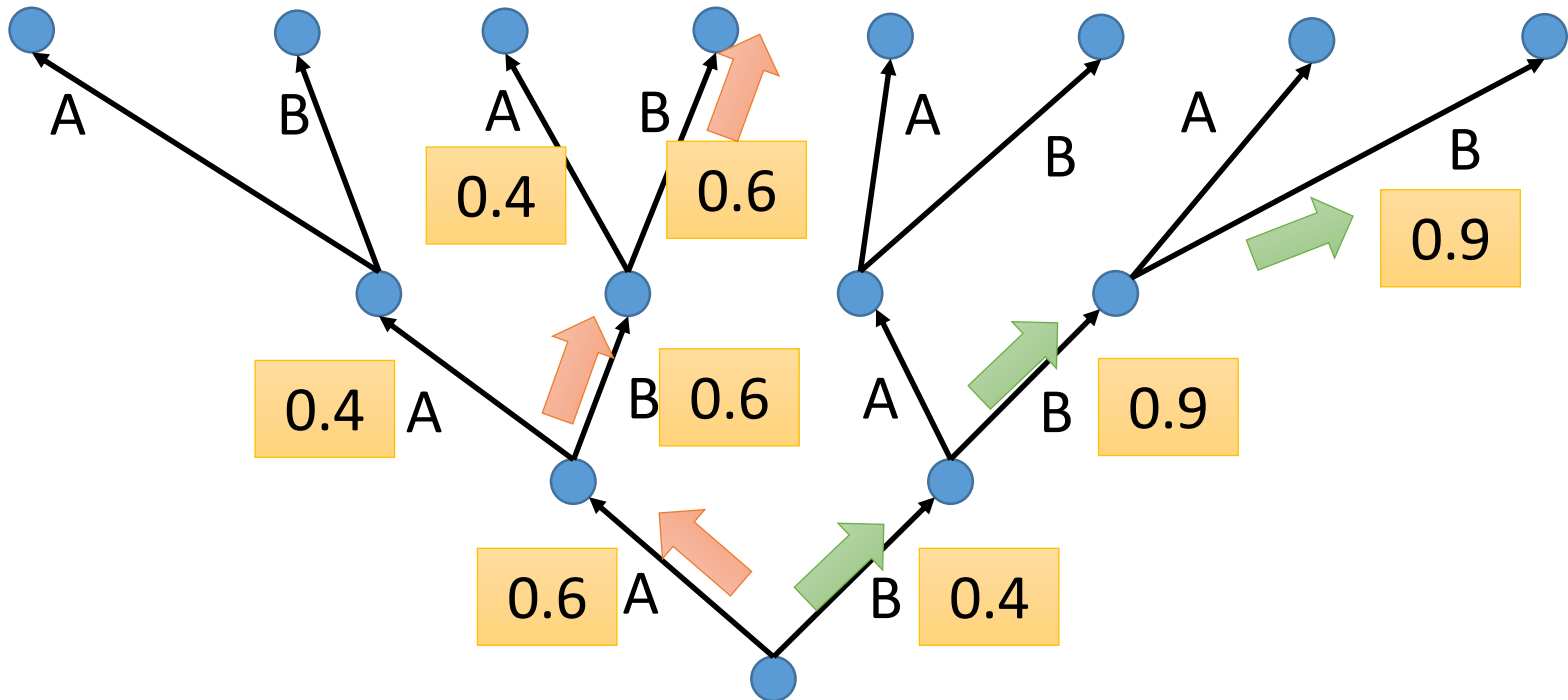
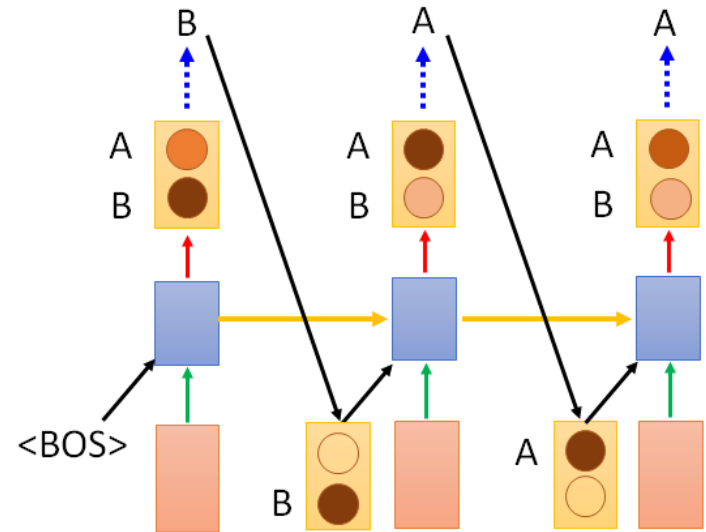
	BLEU-4	METEOR	CIDER
Always from reference	28.8	24.2	89.5
Always from model	11.2	15.7	49.7
Scheduled Sampling	30.6	24.3	92.1

Samy Bengio, Oriol Vinyals, Navdeep Jaitly, Noam Shazeer, Scheduled Sampling for Sequence Prediction with Recurrent Neural Networks, arXiv preprint, 2015

Beam Search

The green path has higher score.

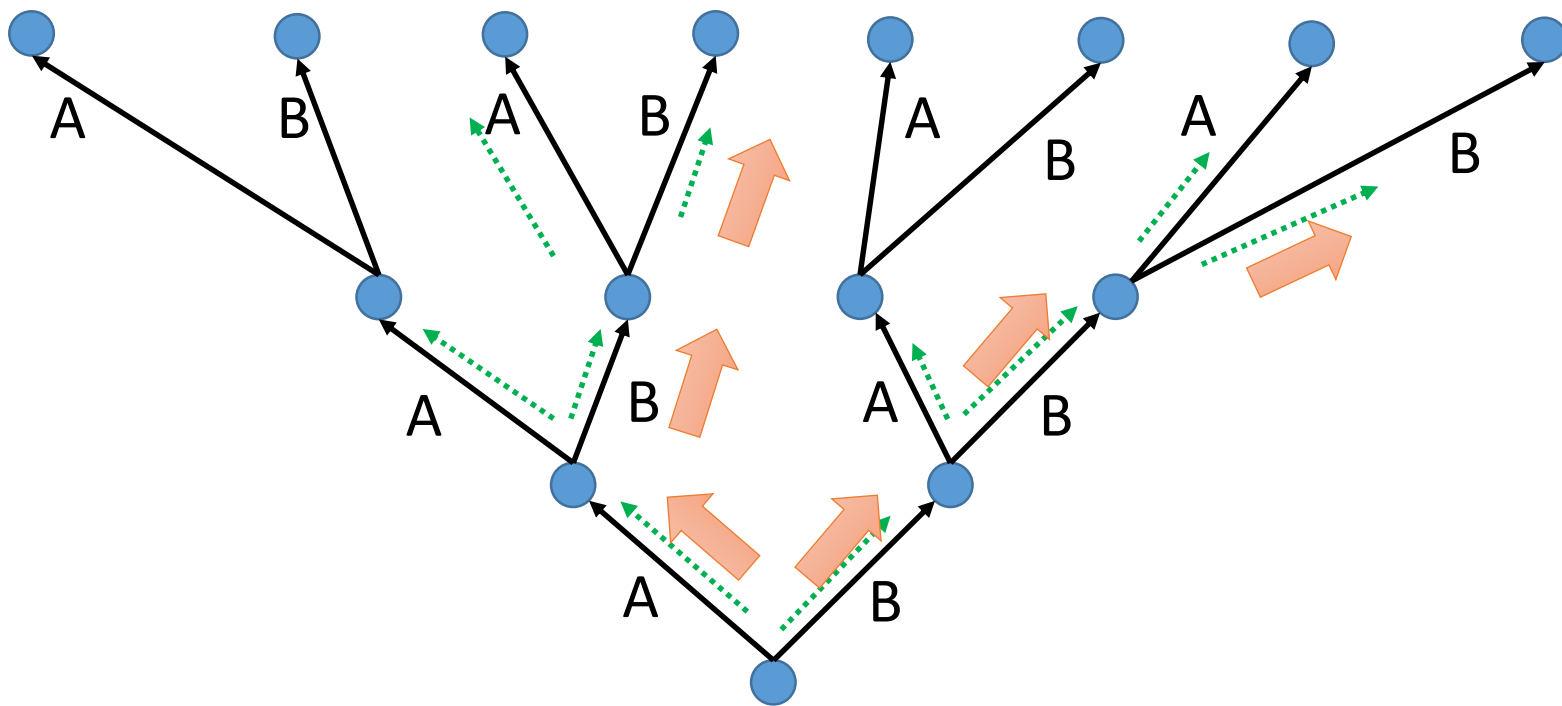
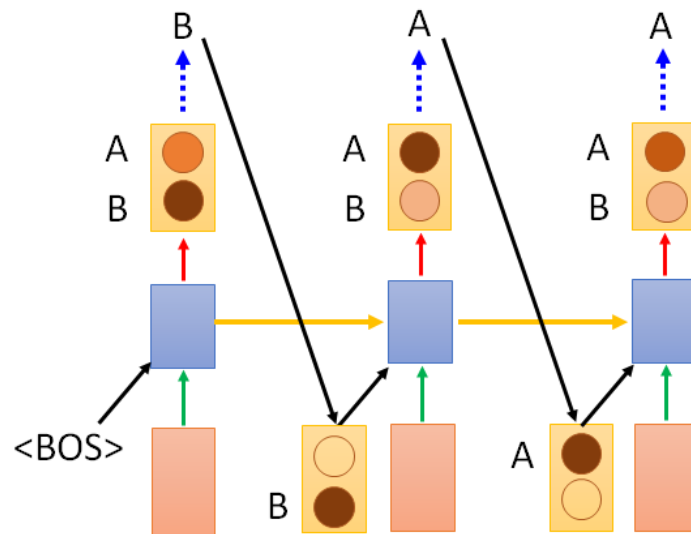
Not possible to check all the paths



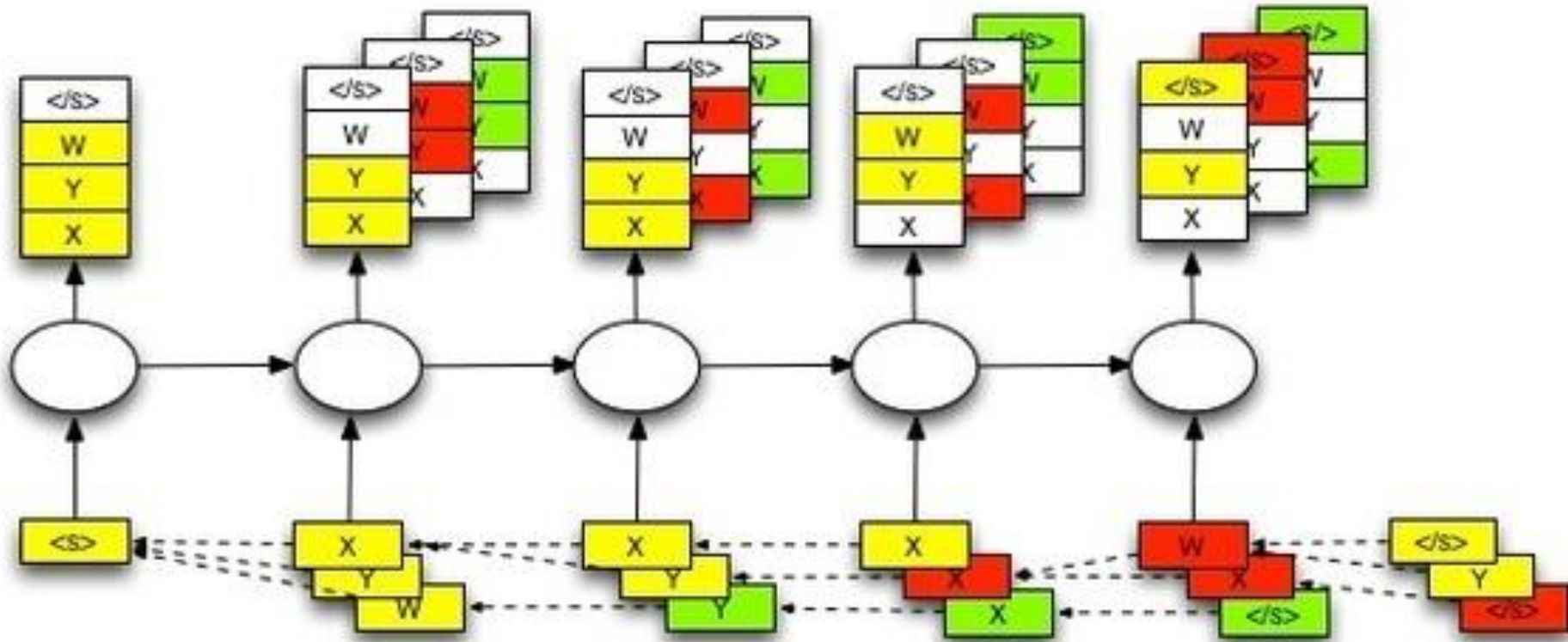
Beam Search

Keep several best path at each step

Beam size = 2



Beam Search



The size of beam is 3 in this example.

Better Idea?

I am



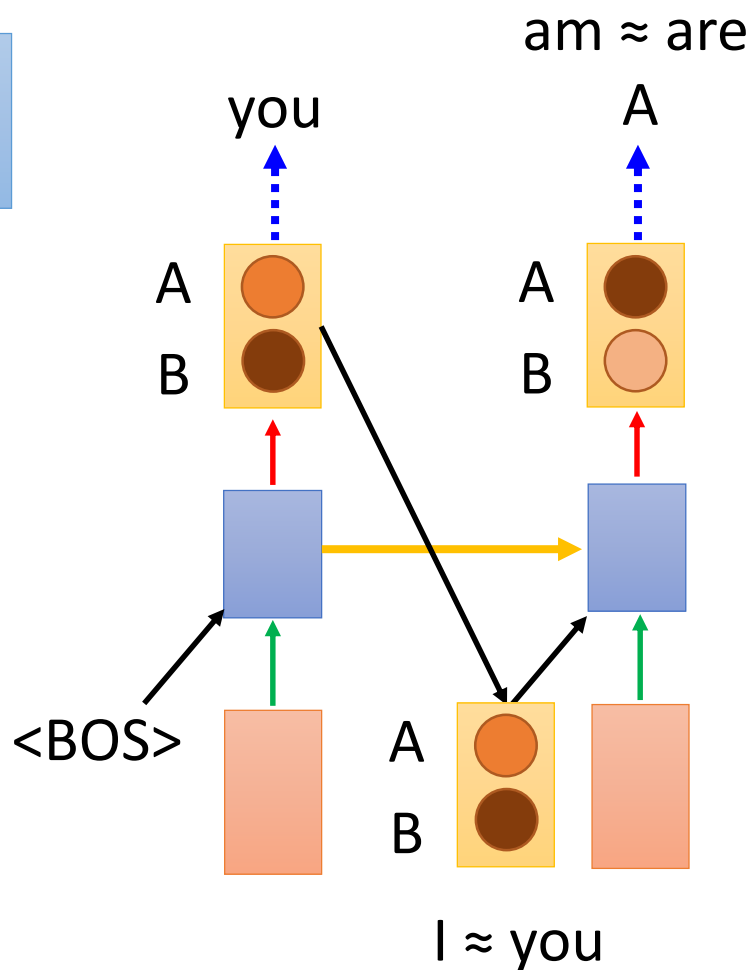
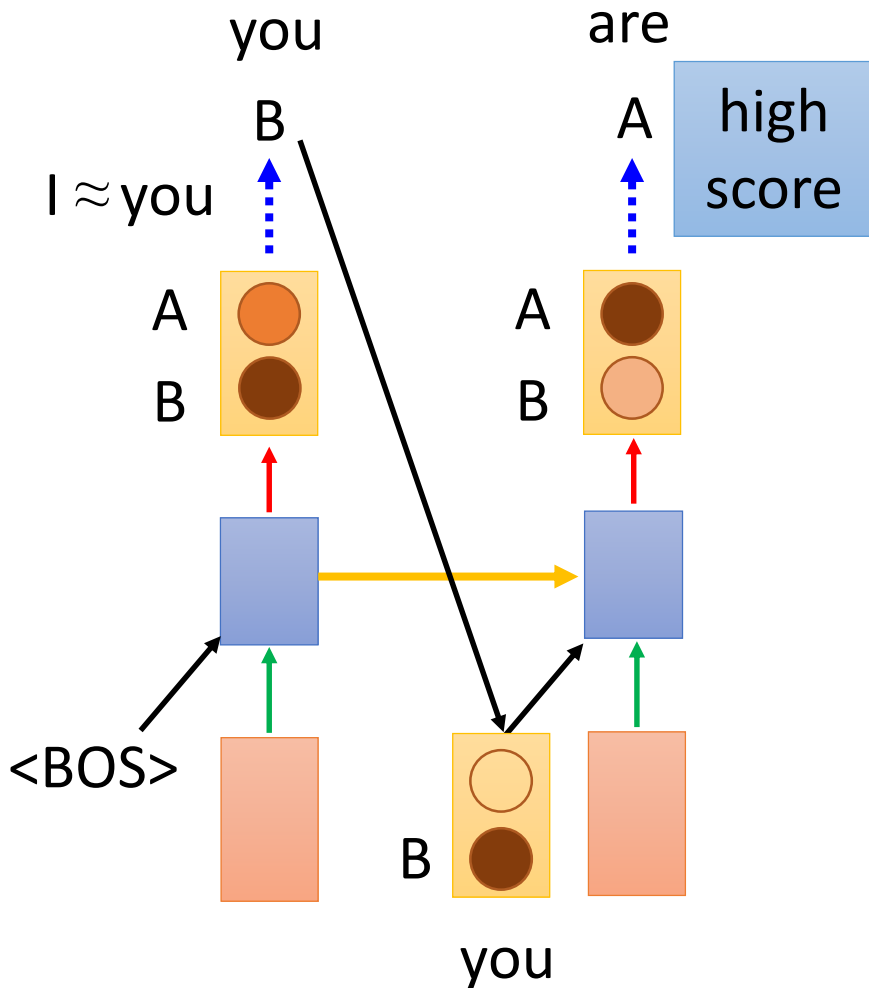
You are



I are



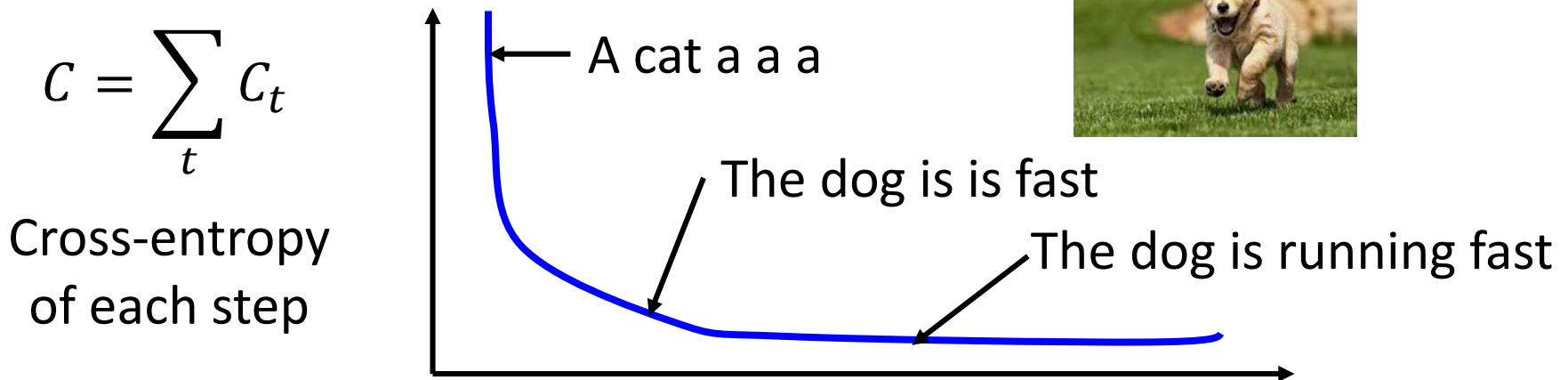
You am



Object level v.s. Component level

- Minimizing the error defined on component level is not equivalent to improving the generated objects

Ref: The dog is running fast



Optimize object-level criterion instead of component-level cross-entropy. object-level criterion: $R(y, \hat{y})$

Gradient Descent?

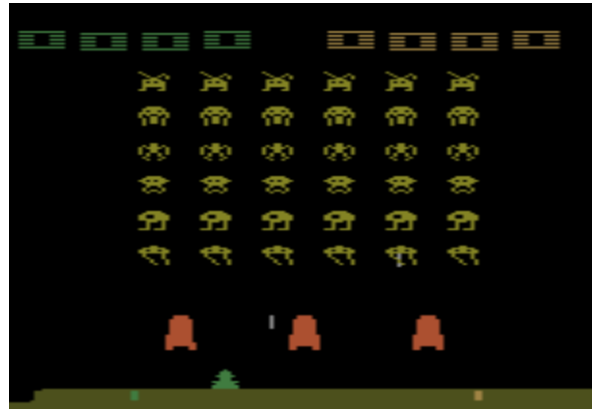
y : generated utterance, \hat{y} : ground truth

Reinforcement learning?

Start with
observation s_1

Observation s_2

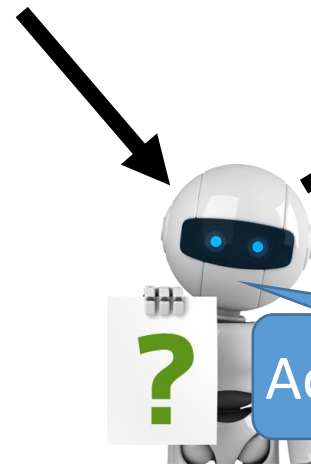
Observation s_3



Obtain reward

$$r_1 = 0$$

Action a_1 : "right"



Obtain reward

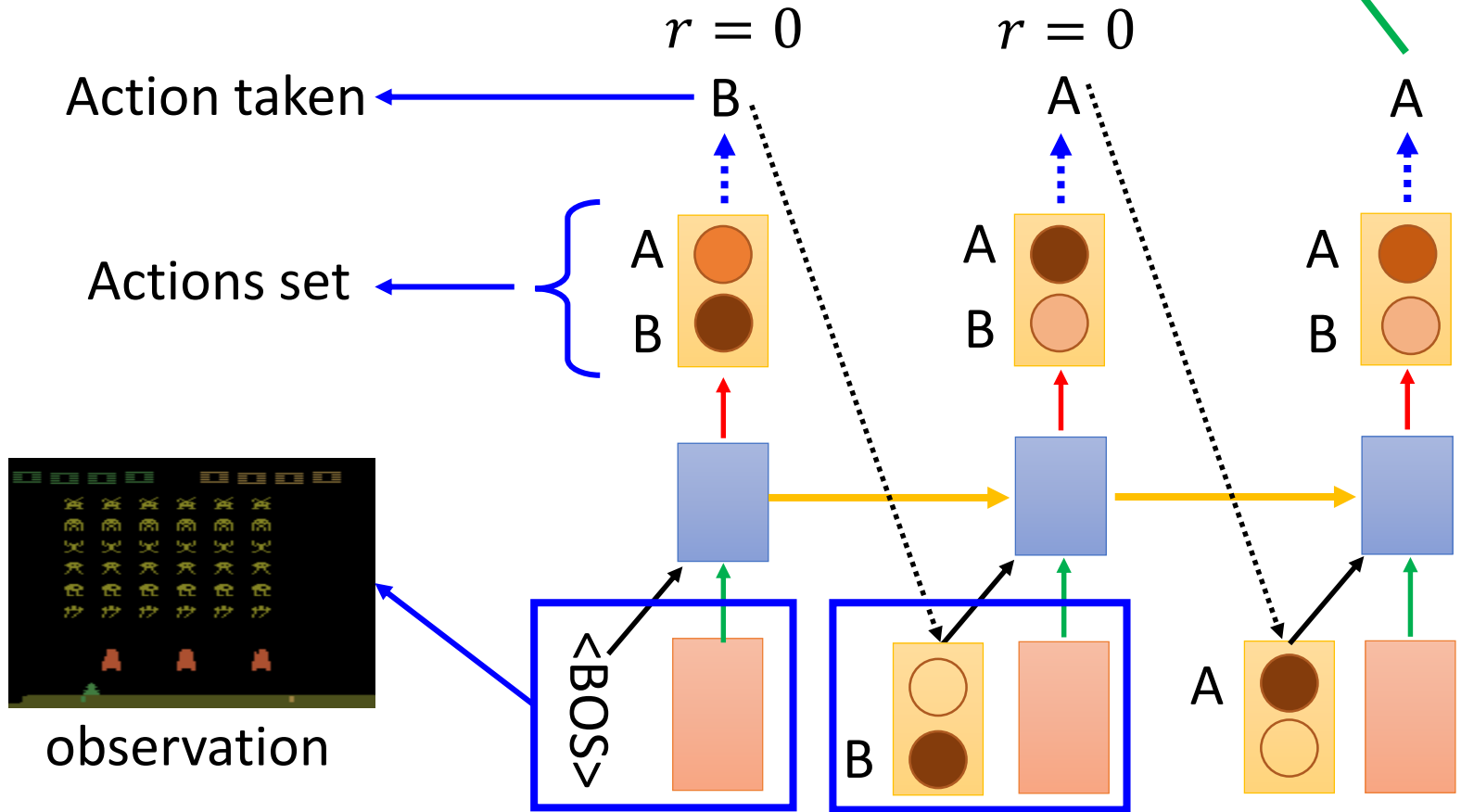
$$r_2 = 5$$

Action a_2 : "fire"

(kill an alien)

Reinforcement learning?

reward:
 $R(\text{"BAA"}, \text{reference})$



Action taken

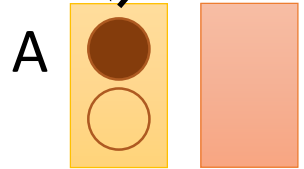
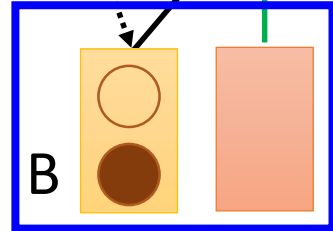
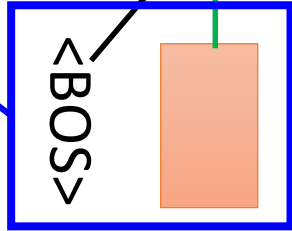
Actions set

$r = 0$

$r = 0$



observation



Marc'Aurelio Ranzato, Sumit Chopra, Michael Auli, Wojciech Zaremba, "Sequence Level Training with Recurrent Neural Networks", ICLR, 2016

The action we take influence the observation in the next step

Concluding Remarks

- RNN with Gated Mechanism
- Sequence Generation
- Conditional Sequence Generation
- Tips for Generation